RF to DC Converter in SiGe Process

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I. Introduction

Wireless sensor chips have many applications including biomedical monitoring, distributed sensors within civil infrastructure and for sensors implanted within the body. Wireless communication and powering of sensors has been accomplished in small modules, but not completely on chip as traditional power sources are too large and bulky. One approach to a chip sized wireless power source is a telemetry system to power the sensor. Wireless telemetry systems require the use of an antenna which will inductively couple power onto the chip.

Previous work in this field includes that done by Huang et. al [1], Marschner et. al [2] and Schuylenbergh & Puers [3]. Marschner separates the transmitter and energy reception into two different off-chip antennas. Huang and Schuylenbergh & Puers both condense their design to use only one antenna, but in both cases they are still off-chip and the frequency of operation is very low. At high enough frequencies the antenna length requirement decreases, enabling it to be placed entirely on chip. This section of the paper contains the design and test of a circuit to be used at these very high frequencies with all on-chip components. Circuit simulation was done through spectre with layout and fabrication through the spring 2002 and beginning of fall 2002 semesters. Fabrication was completed in February 2003, with chip characterization completed by summer 2003. The results showed a constant regulated voltage output that was higher than expected due to process variations. The bandgap circuit showed a constant voltage output that matched simulation data, though the startup voltage necessary to obtain this functionality was higher than expected. Future work includes using high breakdown voltage transistors as well as larger transistors and capacitors for operation at both low and high input voltages.

II. Circuit Design

II.1 Overall Topology

The overall topology of the circuit is shown below in Figure 1. The rectifier provides the initial RF to DC conversion and can provide a wide range of output voltages. However, this voltage output is not stable and is very sensitive to the output load. The transmit block can either short or open the antenna thru switch S_1 to either reflect or receive the RF signal respectively. The regulator provides a constant DC power supply rail regardless of the sensor load.

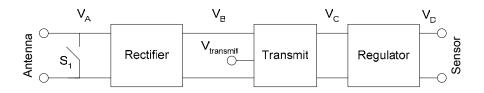


Figure 1. Overall Topology

II.1.A Rectifier Topology & Design

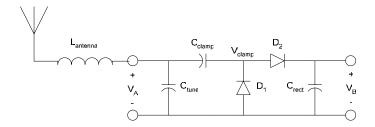


Figure 2. Rectifier Topology

The rectifier shown in Figure 2 is composed of a resonant loop to match and filter the input as well as a decoupling capacitor and a voltage doubling rectifier. There is also a capacitor across

the rectifier to low-pass filter and smooth the rectified output. The tuning capacitor is sized to resonate with the inductance of the antenna by using equation 1 where f is the frequency of operation and $L_{antenna}$ and C_{tune} are taken from Figure 2.

$$2\pi f = \frac{1}{\sqrt{L_{antenna} * C_{tune}}}$$
 {1}

 C_{clamp} and D_1 form the negative clamp while C_{rect} and D_2 form the peak rectifier. The negative clamp serves to raise the average sine wave voltage by preventing V_{clamp} from going below negative one diode drop (~-0.7 V). Thus, a sine wave at the input with an amplitude of 2 V resulting from the LC resonator at V_A would look like a sine wave with a range from -0.7 V to 3.3 V at V_{clamp} . It should be noted that a sine wave with an amplitude less than -0.7 V would never turn D_1 on, and thus would not be affected by the clamp circuit. The peak rectifier takes this sine wave and converts it to a DC signal that is equal to the highest voltage minus one diode drop. So, from the previous example the 2 V amplitude wave would have a resulting 2.6 V rectified output. These signals can be seen below in Figure 3. It should again be noted that if the input since wave has an amplitude less than 0.7 V, D_2 will never turn on and the voltage output will be zero volts.

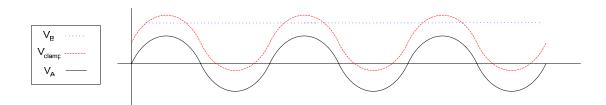


Figure 3. Rectifier Output Waveforms

Sizing of the clamp and rectifier capacitors takes into account the frequency of the input sine wave and the load presented by the rest of the circuitry (regulator and sensor). This load, being in parallel with the rectification capacitor forms an RC time constant of value $R_{load} * C_{rect}$. So, the voltage at the output of the rectifier decreases slowly until the next peak, as can be seen in Figure 4.

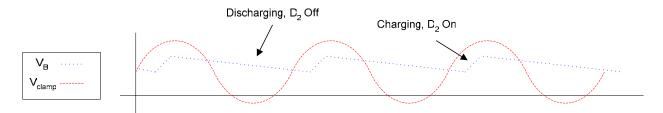


Figure 4. Rectifier Voltage due to Load

Thus, there will be a slight ripple at the output of the circuit and the average DC value will decrease. The ripple can be minimized three different ways: 1) increase C_{Rect} and thus increase the time constant, 2) decrease the load (larger R_{load}) by using low power devices, or 3) increase the frequency of operation such that the period of the waveform is smaller. This third option has the same effect as increasing the time constant. As the ripple peak-to-peak voltage gets larger, the average value of the rectified output gets smaller and thus the regulator might not receive enough voltage at it's input to function properly. So, C_{Rect} should be sized large enough for whatever the application.

For this design, 1pF was chosen for C_{Rect} . R_{load} can be found by applying a DC voltage at the output of the rectifier large enough to turn on the circuitry and measuring the current drawn. For this design this value was 45 K Ω leading to a time constant of 45 ns. This means that at a frequency of 22 MHz the signal will have decreased to nearly 30% of its initial value. This is not acceptable and a good rule of thumb is to operate at over four times this frequency where the

value has only decreased by 2%. For this design therefore, one should only operate above 88 MHz. For more details on the rectifier design, see pages 185 to 197 of [4].

II.1.A.i Rectifier Transistor Choice

The rectifier diodes are implemented as SiGe NPN transistors in the current design. Before deciding the transistor sizing, a fundamental SiGe NPN transistor issue should be discussed. For maximum unity gain frequency (f_T), high frequency SiGe NPN transistors require a large emitter current density. This is usually on the order of $1\text{mA}/\mu\text{m}^2$. However, the maximum current handling capacity of the transistor typically occurs very soon after the point of maximum f_T . This behavior can be seen in Figure 5, f_T vs. emitter current for a hypothetical transistor with an emitter area of $1\mu\text{m}^2$, 50 GHz peak f_T at a current density of $1\text{mA}/\mu\text{m}^2$ at peak fT and a maximum current of 5mA. Actual data can be obtained from pages 100-106 of [5] for the 6HP process and page 19 of [6] for the Jazz process and are not repeated here due to non disclosure limitations.

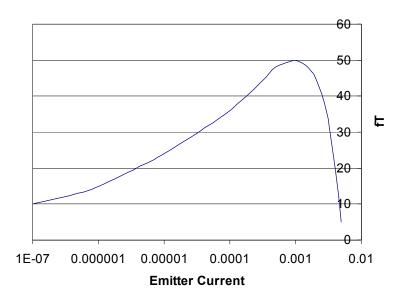


Figure 5. Hypothetical f_T vs. Emitter Current

Therefore, for maximum frequency of operation we should operate the transistors as close to their maximum unity gain point as possible. If the load of the rectifier is well known, we may size the transistors such that they yield a peak f_T and the rectifier will be operable at very high frequencies. If the load is unknown, the transistor should be sized large enough such that the maximum current that can be delivered to the load does not exceed the transistors maximum current handling capacity. The size of the capacitors does not affect this frequency dependency because if the transistors cannot supply enough charge each cycle, the rectified voltage will drop regardless of the charge capacity of the circuit.

II.1.B Regulator Topology & Design

The regulator shown in figure 6 was chosen for its high over-current protection and low internal power dissipation. It is composed of a Bandgap voltage source to provide the reference voltage, an Operational Amplifier to servo the Bandgap voltage (V_{Ref}) to a resistor chain (V_X), and a PMOS pass transistor to compensate for different loads. Sizing the resistor chain according to equation 2 can give any value of V_D necessary at the output of the regulator (and the entire RF-DC converter), given that the rectified voltage will be higher than the final V_D . If the OpAmp has enough gain, the voltage V_{Ref} will appear at V_X . V_D may be found by a voltage divider equation. For this design a V_D of 3.0 Volts was chosen.

$$V_X = V_D \frac{R_{R2}}{R_{R1} + R_{R2}} \longrightarrow V_D = V_{Ref} * \left(1 + \frac{R_{R1}}{R_{R2}}\right)$$
 {2}

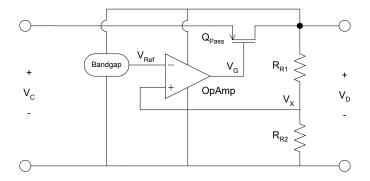


Figure 6. Regulator

There is a fundamental tradeoff between the area of Q_{Pass} and maximum available current. The larger the transistor, the more current it can source without driving the OpAmp output into a non-linear region. Equation 3 shows the relationship between the current and the voltage from gate to source (V_{GS}).

$$i_D \cong \frac{\mu_n W C_{ox}}{2L} (V_{GS} - V_T) * (V_D - V_C)$$
 {3}

As the current increases, the voltage from gate to source increases. Since the source is at a fixed potential the gate voltage drops, thus driving the output of the OpAmp lower and lower. When this output reaches the low end of the output swing rang of the OpAmp, it no longer functions in a linear manner and the regulator cannot increase the current to the load beyond this limit. For this design, the maximum current was set to 1mA with a size of W/L = 60 / 0.5.

Another way to think of the tradeoff between area and current is by examining the relationship between the resistance of Q_{Pass} and its V_{GS} . A larger current requires a smaller resistance in order to maintain the same V_{DS} . As can be seen from equation 4 (resistance from drain to source of a transistor in deep triode), the smaller the resistance, the larger V_{GS} must be.

$$R_{DS} = \frac{1}{\mu_n C_{ox} \frac{W}{I} (V_{GS} - V_T)}$$
 {4}

II.1.C Bandgap Topology & Design

The bandgap reference as shown in figure 7 is designed to provide a constant voltage of 1.18V regardless of temperature variations and is inspired by a bandgap topology by Rincon-Mora [7]. Semiconductor physics states that if two bipolar transistors operate at unequal current densities, then the difference of their base-emitter voltages is equal to V_T * In ΔI_S (current density ratio). Thus, while the base to emitter voltage of each transistor decreases with temperature their difference is proportional to absolute temperature (from p382-3 of [8]).

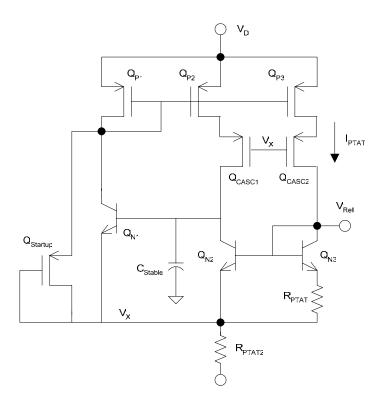


Figure 7. Bandgap Reference

In this topology, this difference appears across resistor R_{PTAT} . Since the resistance value of a resistor increases with temperature according to equation 5, the resulting current (voltage divided by resistance R_{PTAT}) will be constant regardless of temperature. This current is mirrored such that the current through R_{PTAT2} is constant as well. The voltage across R_{PTAT2} therefore increases with temperature while the voltage from emitter to base of Q_{N2} decreases. Since the output voltage is equal to these two voltages added together it remains constant through temperature changes.

$$R = R_{NOM} * TC * T(^{\circ}C)$$
 {5}

 R_{PTAT} is sized by equation 6 where C is the ratio of the size of Q_{N3} to Q_{N2} (ΔI_S) and I_{PTAT} is a current that is chosen by the designer. The current should be chosen as a tradeoff between power consumption and output current. Since a requirement of the bandgap operation is for equal current flow through both Q_{N2} and Q_{N3} the output current must be negligible compared to I_{PTAT} . The value of C is chosen as a tradeoff between area and reliability. Large values mean a large area for Q_{N3} , however a deviation in the value of C will have less impact than if the same deviation appeared with a smaller value of C. For the design presented in this report a value of 5.4 K Ω was chosen as R_{PTAT} for a current of $10\mu A$ and a ratio of 8 between the transistors. R_{PTAT2} is chosen by equation 7 and is $13.5 \text{ K}\Omega$ in this design.

$$R_{PTAT} = \frac{Vt * \ln C}{I_{PTAT}} \tag{6}$$

$$R_{PTAT2} = \frac{V_{\text{Ref}} - V_{BE-QN2}}{3*I_{PTAT}} \tag{7}$$

The turn-on voltage of this topology is obtained from equation 8 (where saturation voltage for a MOSFET is equal to ΔV_{GS}). From this equation we see a direct relationship between the sizes of both the mirror transistors as well as the cascode transistors. Increasing the sizes (W/L ratio) of either of these transistors yields a lower turn-on voltage. For the sizing of W/L = 1/1 for this design, at a current of $10\mu A$, the turn-on voltage is designed to be 2.6 Volts.

$$V_{Turn-On} = V_{DS-Sat}(mirror) + V_{DS-Sat}(casc) + V_{REF} = \sqrt{\frac{2I_D}{\mu_n C_{ox}} * \frac{L_{mirror}}{W_{mirror}}} + \sqrt{\frac{2I_D}{\mu_n C_{ox}} * \frac{L_{casc}}{W_{casc}}} + V_{REF}$$
 (8)

The cascode transistors are an optional addition and are added to shield the PFET current mirror transistors from large voltages output from the large rectifier voltage. In the SiGe 6HP process used, this would enable a working voltage up to approximately 6.6 V (equation 9 with $V_{break-down}$ = 2.7 V from [5]), as opposed to 4 V (equation 9 with only one breakdown voltage) if they were not added. Another approach would have been to use higher break-down voltage transistors (up to 3.5 V in this process). C_{Stable} (the capacitor connected to the base of Q_{N1}) is used to stabilize the input voltage to that transistor and should be sized through circuit simulation. Finally, the startup transistor $Q_{startup}$ is chosen to have a very small W/L in order to take as little current away from Q_{N1} as possible. For this design W/L is chosen to be 1/5.

$$V_{Max} = V_{REF} + 2 * V_{break-down}$$
 {9}

The bandgap is extremely sensitive to resistive loading, as the nominal current through each branch is only $10\mu A$. Since there is a current mirror driving each branch, if any DC current is used to drive an output it will starve Q_{N3} of current, causing the circuit to malfunction. In order to minimize this sensitivity one could increase the current in each branch, thus increasing the load current necessary to cause failure. In this design, the bandgap drives a FET input, and thus can operate on a very low current level ($10\mu A$).

II.1.D Opamp Topology & Design

The specifications for the OpAmp need not be very high for this application so a standard one stage Opamp with a gain of over 60dB was designed (see figure 8). This reduces the number of poles and aids in assuring stability. Since the circuit operates at low frequencies, bandwidth is not a large consideration. The bias is provided by the bandgap reference to ensure reliable performance under temperature variations. Power and area were minimized such that the design uses 150µA and is approximately 120µm².

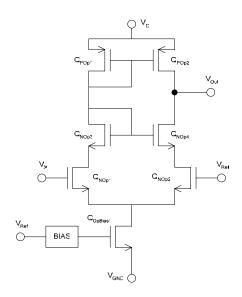


Figure 8. Opamp

The turn-on voltage for the Opamp is given by a similar equation to equation 8 and is equal to 2.7 Volts. The output swing is equal to V_{DS-SAT} of Q_{POp2} at the high end and the summation of V_{DS-SAT} of the lower three NFET transistors. This becomes a swing of 0.6 V to $(V_D - 0.3)$ V.

II.1.E Transmission

Data transmission is accomplished by either shorting or opening the antenna and having the external RF source look at the reflected radiation. This is accomplished via a bipolar switch which either shorts the antenna or allows power to be drawn into the circuit. An MOS switch is also present, stopping the charging of storage capacitors C_{Clamp} and C_{Rect} (from Figure 2) for the reflection case or keeping the antenna open and continuing to charge the storage capacitor in the other case. Shown below is the schematic of the transmission circuit. It connects in series between the rectifier and regulator and will generally just pass the rectifier voltage to the regulator when $V_{transmit}$ is low. Inverters INV_1 and INV_2 serve as a buffer between the electronics (which may not be able to supply enough current to turn on Q_{S1}) and the switch S_1 .

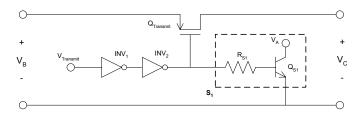
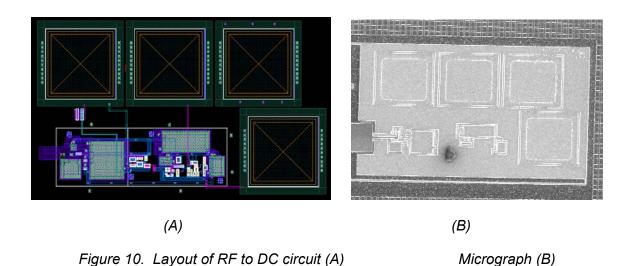


Figure 9. Transmission Circuit

II.2 Chip Layout & Extraction

II.2.A Layout

The layout of the circuit is shown in Figure 10. The pads are shown on the outside with the circuitry in the lower left. The pads correspond to $V_{transmit}$, $V_{bandgap}$, GND and V_{D} from left to right. The total area is $650\mu m$ by $450\mu m$.



The entire chip is shown in Figure 11. There are two copies of the antenna + circuitry, laid out in opposite directions of each other. They are nearly identical with the difference being the circuit on the left does not include the shunt switch (Note that there are only three pads- there is no need for $V_{transmit}$).

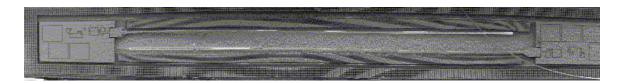


Figure 11. Micrograph of entire chip

II.2.B Ground Connection

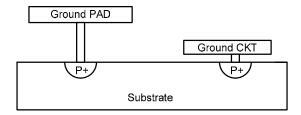


Figure 12. Mistake in Ground Connection

A mistake was made during layout in the ground connection of the chip. Instead of connecting the ground pad directly to the on-chip ground of the circuit, the two are connected 'thru' the substrate via substrate connections on both the pad and the on-chip ground line (see Figure 12). This essentially adds a resistive path between the two which is a combination of the resistance through the substrate contacts and then through the substrate itself. The value of the substrate contact resistance is approximately 40 Ohms, which is an extracted value from the netlist (the netlist gives information about the size of the substrate contact and by creating a separate schematic with that substrate contact in parallel to a voltage source, resistance may be found by measuring the current through the contact). The resistance through the substrate is not currently known due to the fact that substrate resistivity information could not be found in any of the documents available through the Carnegie Mellon MEMS Lab. However, as it is characterized as a low resistance substrate, the value is most likely of the same magnitude or less than that of the substrate contact itself.

This added resistance has the effect of decreasing the power transferred to the circuit from the signal source (HP signal generator or antenna, depending upon which test is being done). As can be seen from figure 13, the amount of power transferred to a device from a 50 Ω source is

highly dependant on the load of the device. As we increase the impedance of the device past 50Ω the total power decreases. This is the case for this device.

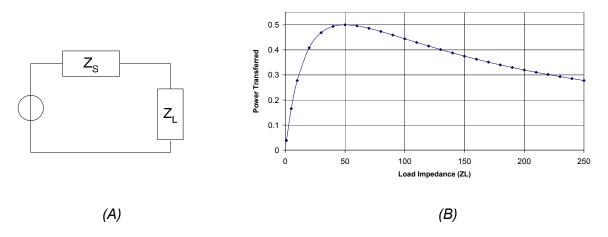


Figure 13. Power Transfer Schematic (A) & Power Transmitted versus Load (B)

The exact effect that this added impedance has can be seen through a simple simulation of the rectifier. In one case (blue curve of figure 14.B) the substrate connection between the on-chip ground and the pad ground is present (as in the actual layout), while in another case it is absent (black curve of figure 14.B). The substrate resistance therefore causes approximately 0.2 V of loss to the input of the rectifier.

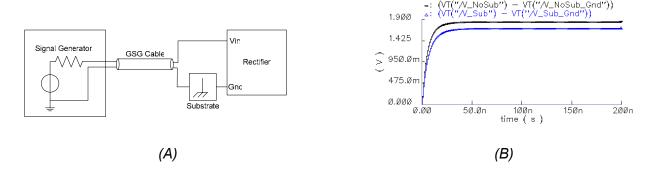


Figure 14. Substrate Contact Schematic (A)

& Rectified Voltage over Time (B)

II.2.C Extraction

Due to the long length of the antenna, there is much added capacitance to the input node of the circuit. This changes the total input capacitance of the circuit from 90 fF to over 850 fF. This changes the center frequency of operation due to the increased LC product at the input. This is the most significant extracted parameter as most of the rest of the circuitry operates at DC exclusively, so any added capacitance will yield better results (less noise and more stability). These parasitics, though small, were used nonetheless during testing.

III. Simulation & Experimental Results

III.1 Simulation & Chip Testing Plan

Simulation of the circuit was completed with special attention paid to the testing model. As stated previously (Section II.1.A) the circuit is inoperable at frequencies below 100MHz. Standard probestations would not be able to be used for these high frequencies so an RF probestation with high frequency Signal Generators and GSG probes was used. A model of this test setup was used to simulate the exact signal that would be present in the chip. It is shown in figure 15 below. It includes a port model for the Signal Generator, transmission lines representing the cable and probe, pad models for each probe pad and a resistor/capacitor for each oscilloscope input. Since the bandgap is highly sensitive to any resistive loading (see Section II.1.C) a JFET OpAmp with only a 250pA input bias was used in a basic buffer configuration (input to positive terminal, output connected to negative terminal).

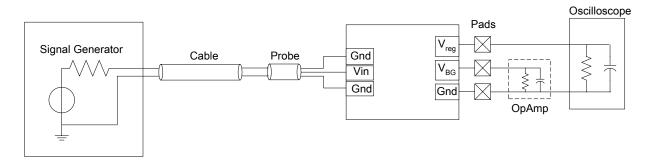


Figure 15. Simulation model

The output of the circuit was probed with standard DC probes and transmitted into an oscilloscope to observe the waveforms. The model used for the circuit was the fully extracted model as discussed in Section II.2.C

III.2 Results

Since this circuit simply outputs a DC signal, there are only a few interesting results that are shown here in graphical form. For regulator results a simulation test setup with the regulator output connected to an oscilloscope model and the bandgap floating was used. For bandgap results a floating regulator voltage with the bandgap output connected to the OpAmp model was used. Simulation amplitudes above 1.4 Volts at the input were unattainable as warnings from Spectre appeared due to transistors entering breakdown regions. Experimental amplitudes were limited by the maximum output of the Signal Generator (3.9 Volts).

The total power consumed for the circuit is $90\mu W$ (Bandgap) + $150\mu W$ (Opamp) + $60\mu W$ (rest of regulator) = $300\mu W$ Total.

III.2.A Regulator Results

The following graph shows the regulated voltage as a function of input amplitude at a frequency of 1 GHz.

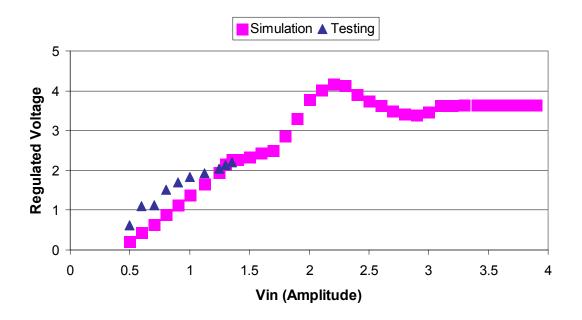


Figure 16. Regulated Voltage vs. Input Amplitude

The transient picture of the regulated voltage output in simulation as well as from the oscilloscope during testing is shown in Figure 17. Simulation was done at the maximum input voltage before warnings (1.4 V) and testing was done at a 3.5 V input. Also included from the simulation are the bandgap and rectifier voltages. The spiking will be explained in section IV.2.

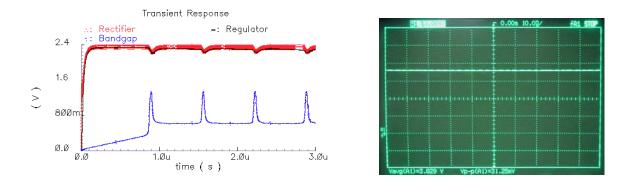


Figure 17. Transient regulator waveforms of simulation (A) and testing (B)

III.2.B Bandgap Results

The bandgap average voltage and peak to peak values compared to the input voltage level for both simulation and testing are shown in figure 18. The outlined points indicate spiking as seen in Figure 17 (A).

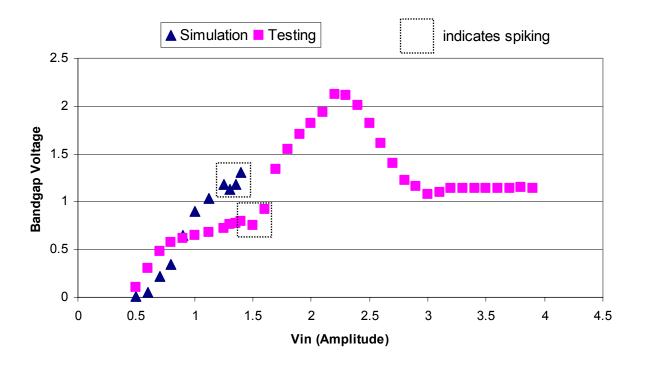


Figure 18. Bandgap Voltage vs. Input Power

Figure 19 shows the oscilloscope picture of the bandgap output at a 3.5 V input from the signal source (HP signal generator) at 1 GHz. The average voltage is 1.14 V.

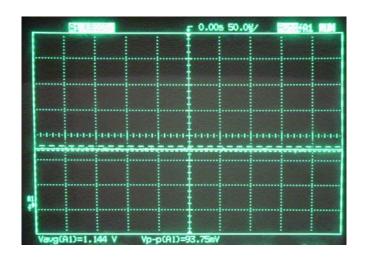


Figure 19. Transient bandgap waveform from testing

For completeness, figure 20 shows a non-functioning bandgap due to low input power and high output bias current (connected to the oscilloscope directly). The simulated transient response of the bandgap at a 1.35V input with a test setup described in section III.2.A is shown in Figure 20(A). Figure 20(B) shows the oscilloscope waveform from testing at a 1 V input at 1 GHz.

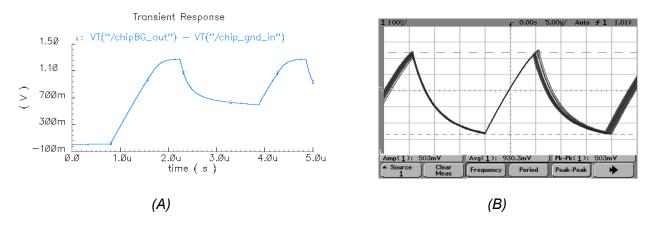


Figure 20. Incorrectly functioning bandgap output. Simulation (A) & Testing (B)

The theoretical voltage range of the bandgap is shown in Figure 21 below. This test is conducted only at simulation level. Since there are no test structures for the bandgap by itself on the chip.

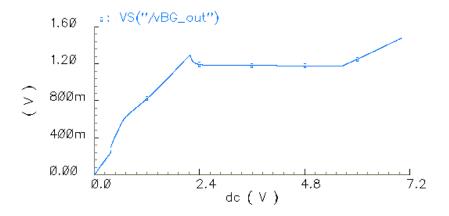


Figure 21. Working Voltage range of Bandgap Circuit

IV. Assessment of Results

IV.1 Regulator Behavior

The regulator functioned well, outputting a DC value of 3.6 Volts over a range of input voltages. This output value was higher than the expected 3.0 volts that the circuit was designed for. This inconsistency can be attributed to resistor inaccuracy due to poor layout. One resistor was divided into three series pieces at minimum spacing from each other, while the other was set as one long piece with no polysilicon to either side. Furthermore, there were no dummy cells and the resistors were laid out in a staggered fashion. This caused a large difference between the two resistances, resulting in a higher than average regulated voltage. Figure 22 is a simplified layout of these two resistors.

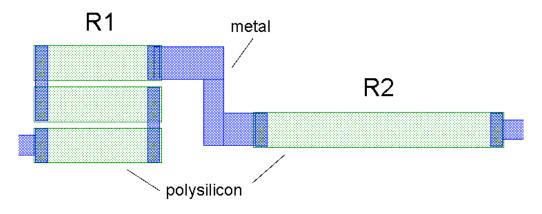


Figure 22. Resistor layout

IV.2 Bandgap Behavior

Two test setups were performed with the bandgap. The first contained a direct connection between the bandgap output and the oscilloscope. The second test setup contained a buffer in the form of a JFET OpAmp such that the bandgap output experiences much less loading.

Oscillation was seen in the first case (Figure 20.A). Spiking was seen in the second case (Figure 17.A). Note that these two phenomena are only visible at low input voltages. As can be seen from testing, at high enough voltages the bandgap operates normally.

The spiking bandgap voltages as seen in simulation and low-voltage testing are due to low input voltages at the bandgap supply. As explained in Section II.1.A, under a load the rectifier average DC value will decrease. When the circuit is first beginning to power-up the bandgap does not draw any current and the rectified voltage increases to a steady level. Once the bandgap begins to draw current and increase the output voltage, the rectified voltage drops due to the sudden load. Once this voltage drops below the threshold voltage for bandgap power-up the bandgap output drops and the rectifier voltage increases back to the steady level it was at

before. The cycle begins again once the bandgap tries to draw current, causing repetitive spikes. At a high enough input voltage level the spiking goes away.

The oscillatory behavior that can be seen in figure 20 occurs when the JFET OpAmp buffer is replaced by a direct connection to the oscilloscope. As in the spiking example, the bandgap tries to power up but the decreasing rectifier voltage causes a drop in output voltage. The difference in the oscilloscope case is that there is a load composed of a 9 pF capacitor and a 1 $M\Omega$ resistor in parallel connected to the output. Since the transistors on the output of the circuit are all in deep triode or are off due to the low voltages, the output must discharge through the oscilloscope. This causes the behavior smooth charging and discharging seen in the results, as compared with the crisp spiking seen with no bandgap load.

V. Conclusions

A functioning RF to DC converter to be used at RF frequencies is presented above. The output from the regulator was higher than expected due to mismatch, but the bandgap output appeared normal. The voltage range was constrained by the transistor breakdown voltages, leading to cascading of devices and higher turn-on voltages. Problems were encountered during testing due to simple mistakes during the pre-fabrication phase, including not shorting the ground pad to the on-chip circuit ground and not matching the regulator resistor chain.

VI. Future Work

In order to meet voltage range requirements and ensure proper circuit performance a few steps should be taken. Since the post-rectifier circuit is mainly one that operates at a DC value, sacrificing high frequency performance for higher voltage range in the transistors should be a top priority. Slower transistors will affect the startup time of the RF to DC conversion, but it will allow much higher voltages without resorting to cascading, which can complicate a circuit.

Concerning the rectifier, not only should the transistors have large breakdown voltages but they need to be large themselves. During the brief recharge period of each cycle a surge of current must flow through the transistors. If the transistors aren't large enough to handle this sudden current they can breakdown or melt.

The circuit also suffered from poor layout design preventing circuit block testing. When the circuit was fabricated no test structures such as a bandgap by itself or a regulator by itself were present in the layout. This would have greatly aided in identifying problems and circuit limitations. Also concerning the layout is the resistor and transistor matching. Dummy cells as well as common gate and transistor widths should be present in the layout.

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