

Towards Feasible Power Delivery On AC Electric Networks Using Smart Wires

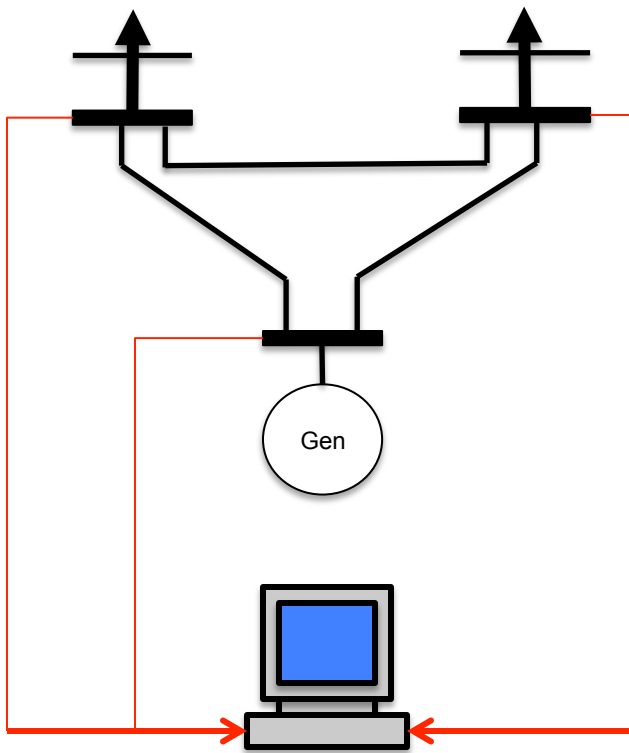
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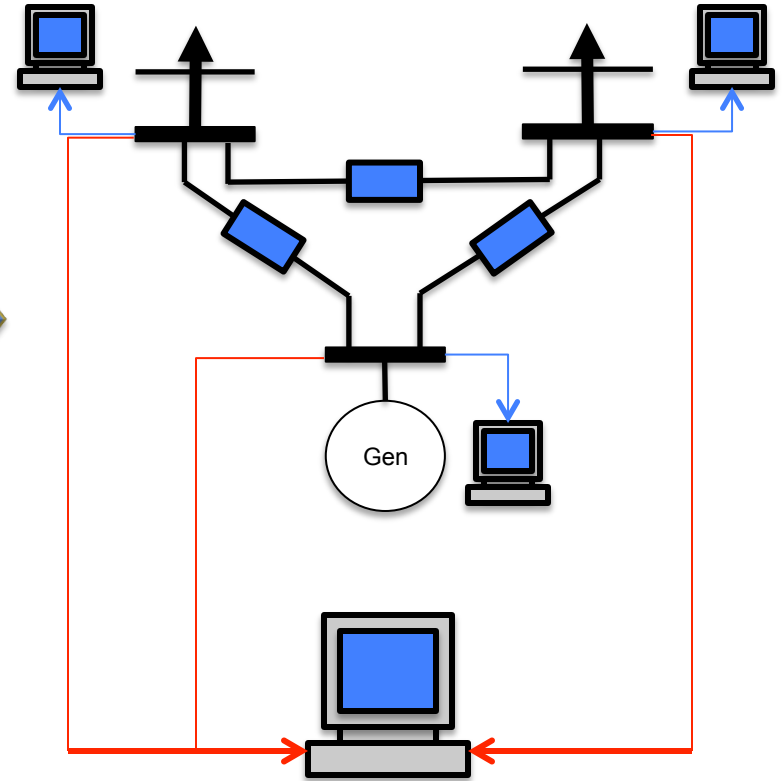
Motivation

- ❖ **Many new wire-based devices that can measure, actuate, and calculate/store data**
 - Dynamic line rating units (DLRs)
 - Distributed series reactances (DSRs)
 - Flexible AC transmission system (FACTS) devices
- ❖ Can distributed, smart, wire-based devices cooperate to perform system calculations?

Grid Components Becoming Smarter

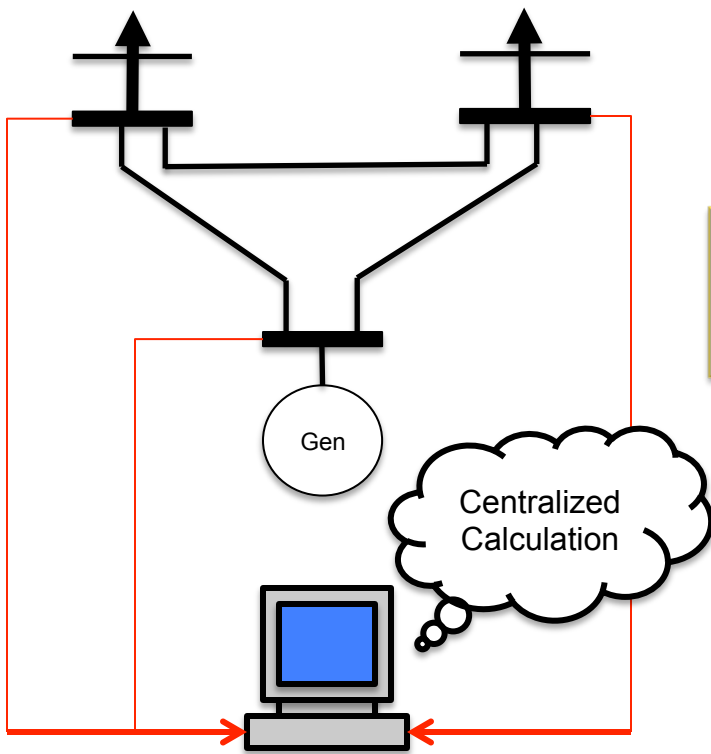


System Operator

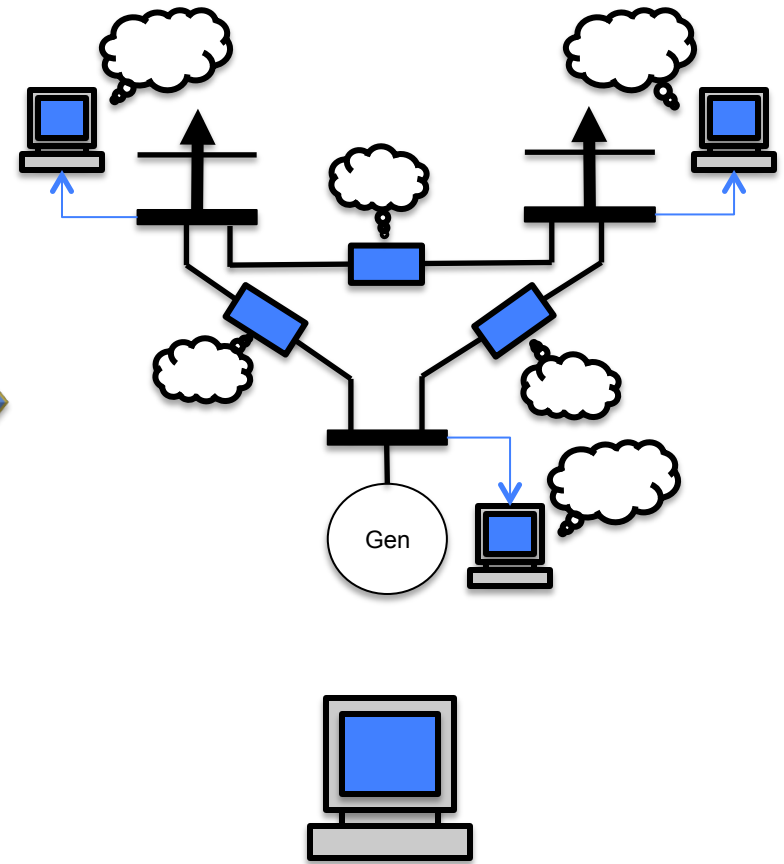


System Operator

Distributed Power Flow

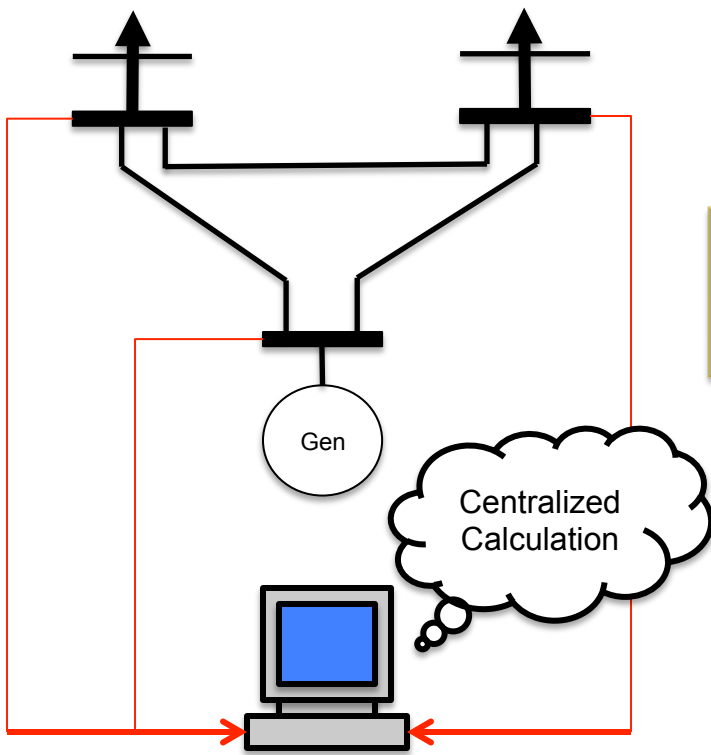


System Operator

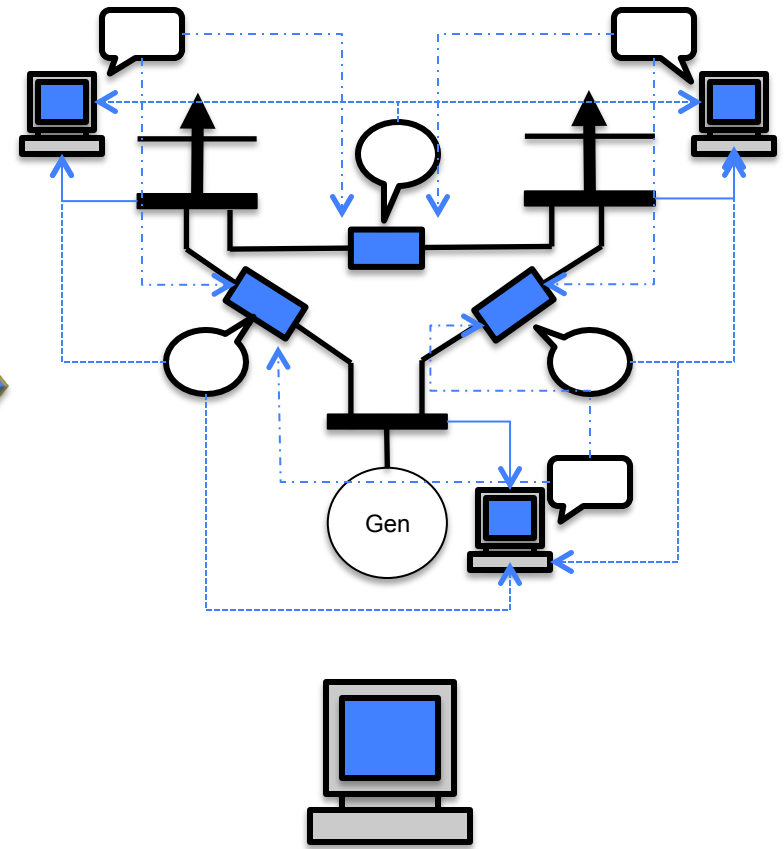


System Operator

Distributed Power Flow



System Operator



System Operator

Potential Uses

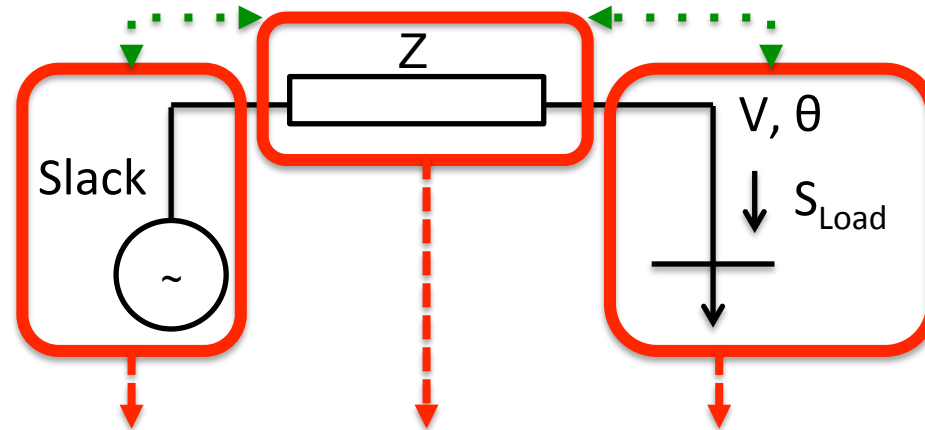
❖ Complement to centralized operator

- Calculate power flow independently^{1,2,3}
- Individual computations easy to carry out

❖ Prevent Infeasible Power Transfer

- No voltage solution for given loads/network
- Hard to calculate in centralized way (except 2 bus)⁴

DPF Algorithm 2 Bus Case



Component Name: Bus1 Line1 Bus2
 Component Type: BusSlack Line BusPQ

Communications Setup Table:

From	Bus1	Line1	Bus2	Line1
To	Line1	Bus1	Line1	Bus2

DPF Algorithm – Bus Modules

◆ Bus Module

□ Properties

- name, type, LinesIn, LinesOut, time, iter
- Variables
 - Vbus, lambda, Dlambda

□ Methods

- Constructor:
 - read params from Matfile
- Calculators:
 - calculate Dlambda, lambda
- Comm. from lines (read()):
 - get mismatches, Sf, Sl, voltages, Vbus (tree status lines)
- Comm. to lines (write()):
 - send Dlambda, lambda, Vbus
- Run function (while loop)

DPF Algorithm – Line Modules

◆ Line Module

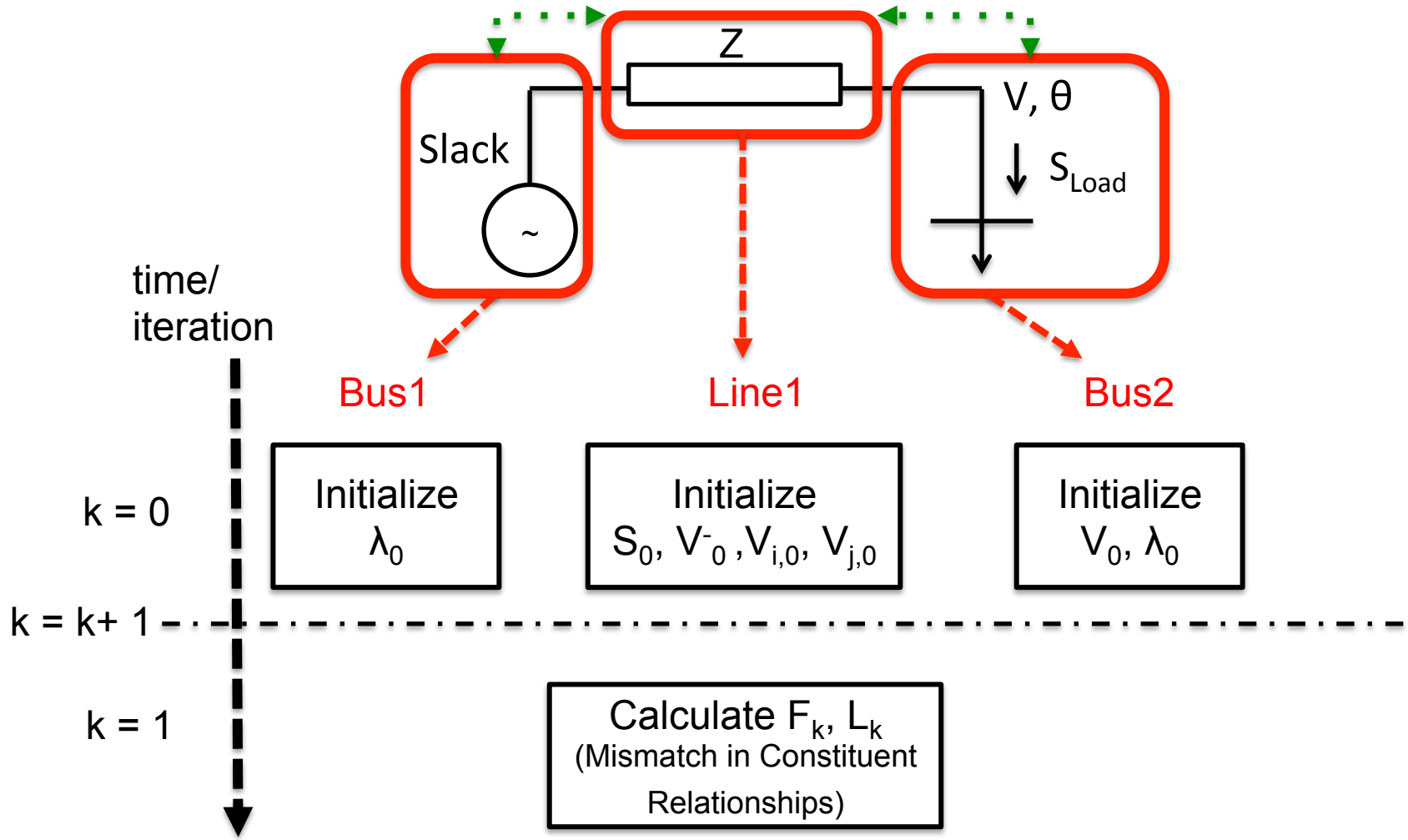
□ Properties

- name, type, busSen, busRec, time, iter
- Variables
 - Z, Sf, Sl, Vacross, VSend, VRec, Fmis, Lmis

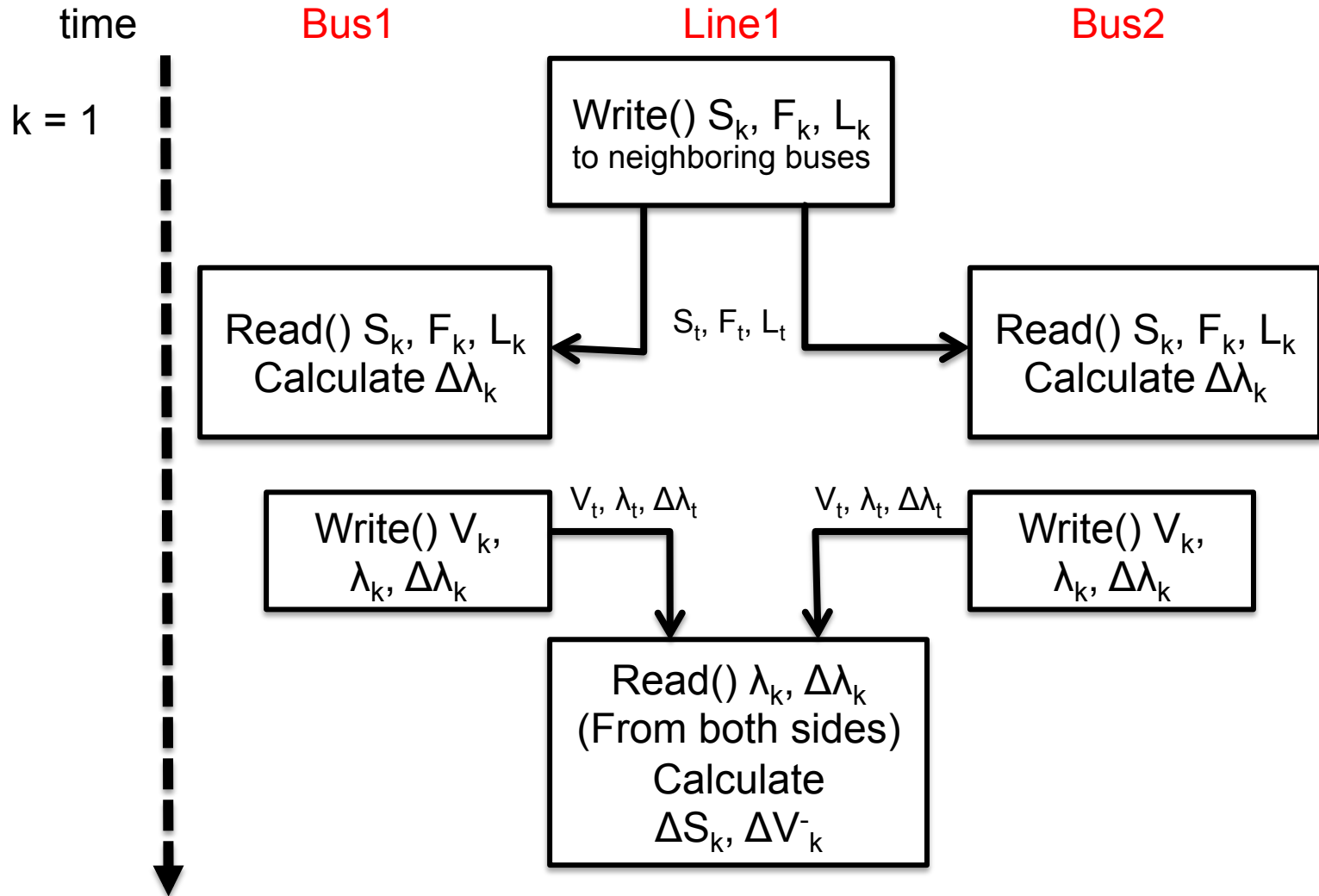
□ Methods

- Constructor:
 - read params from Matfile
- Calculators:
 - calculate mismatches,
 - update S, V
- Comm. from lines (read()):
 - get lambda variables, voltages
- Comm. to lines (write()):
 - send Fmis, Lmis, Sf, Sl, VRec
- Run function (while loop)

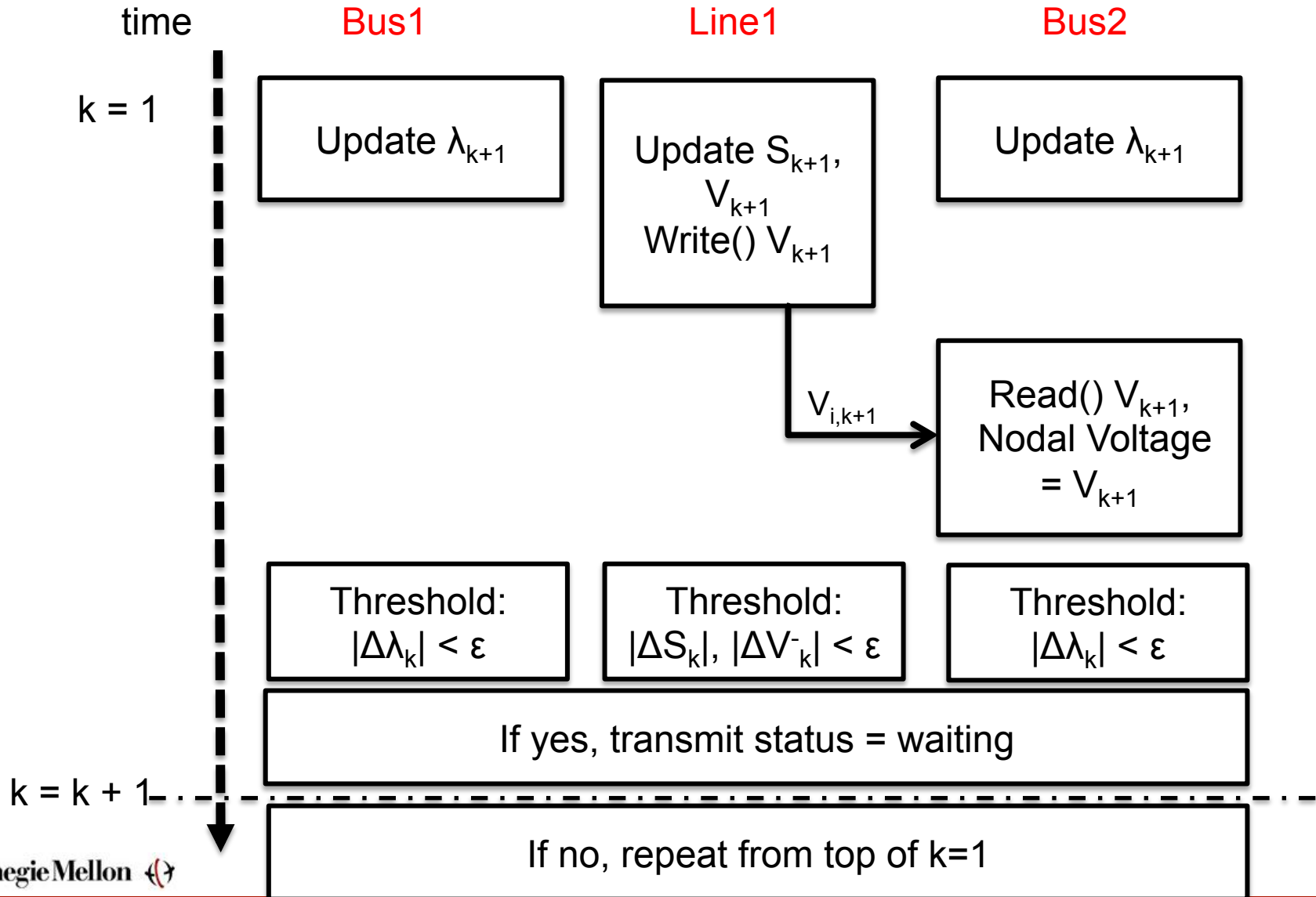
DPF Algorithm 2 Bus Case – Evolution Over Time 1



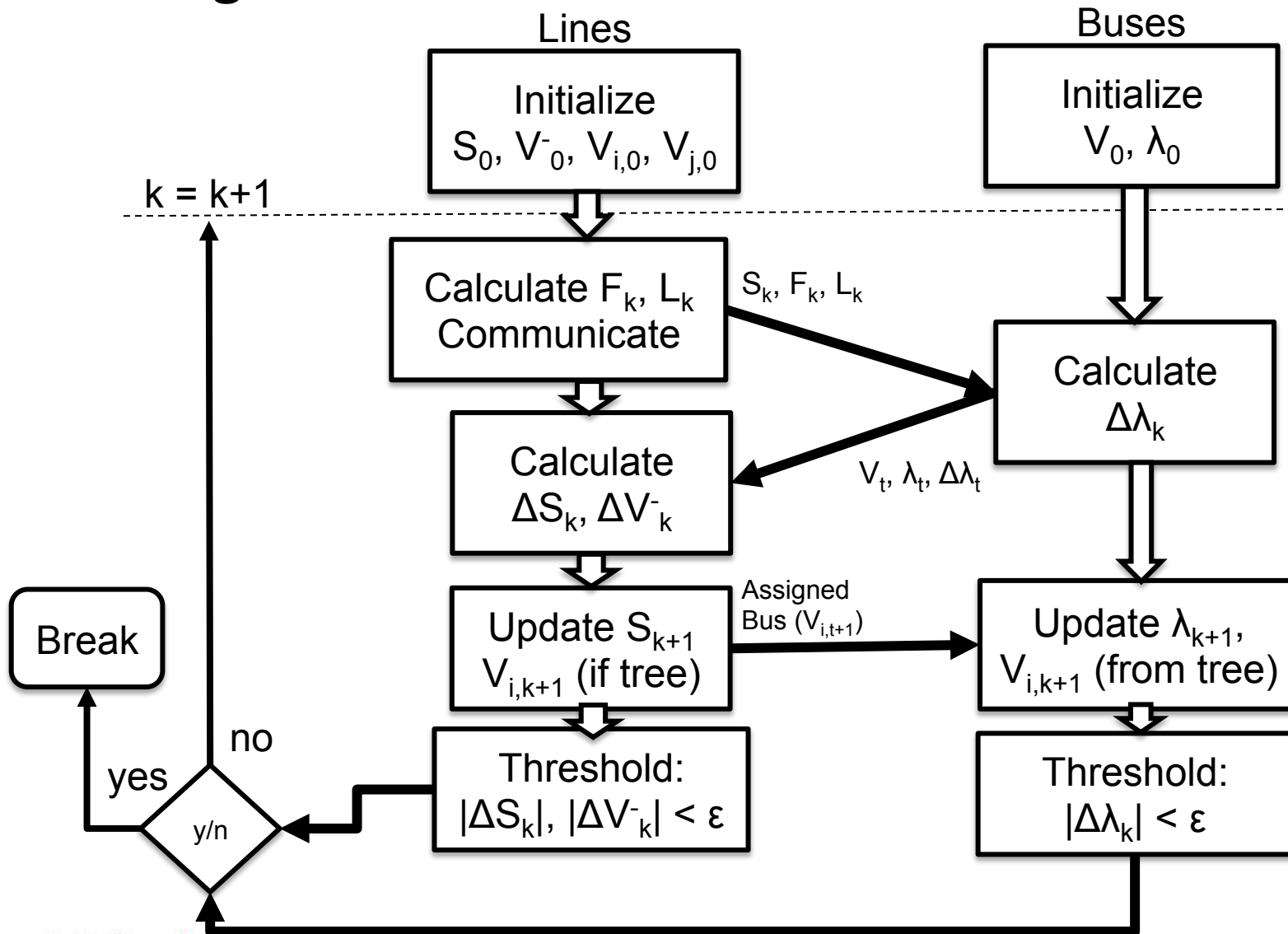
DPF Algorithm 2 Bus Case – Evolution Over Time 2



DPF Algorithm 2 Bus Case – Evolution Over Time 3

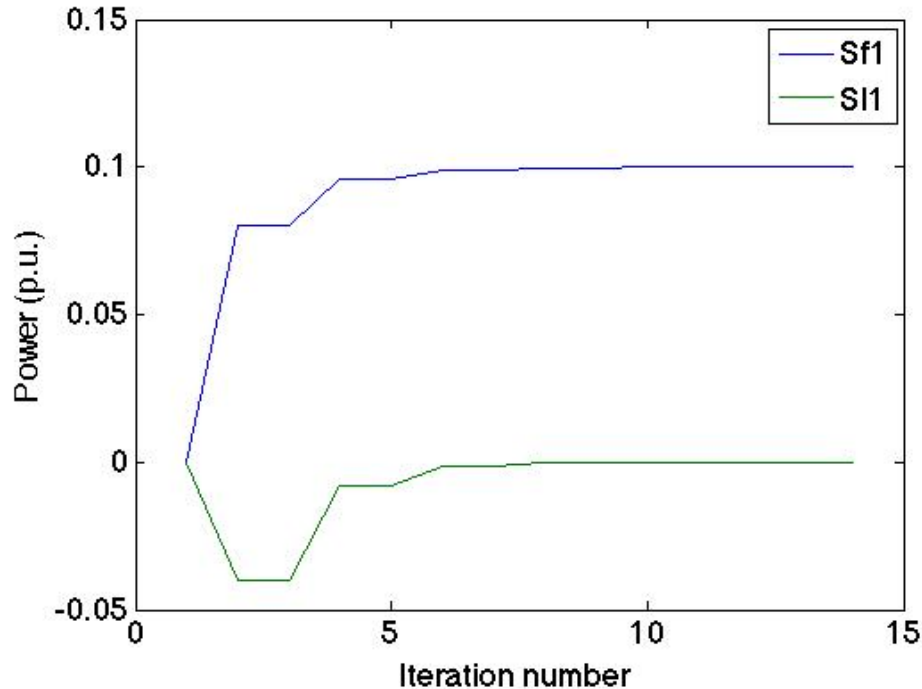


DPF Algorithm Flowchart

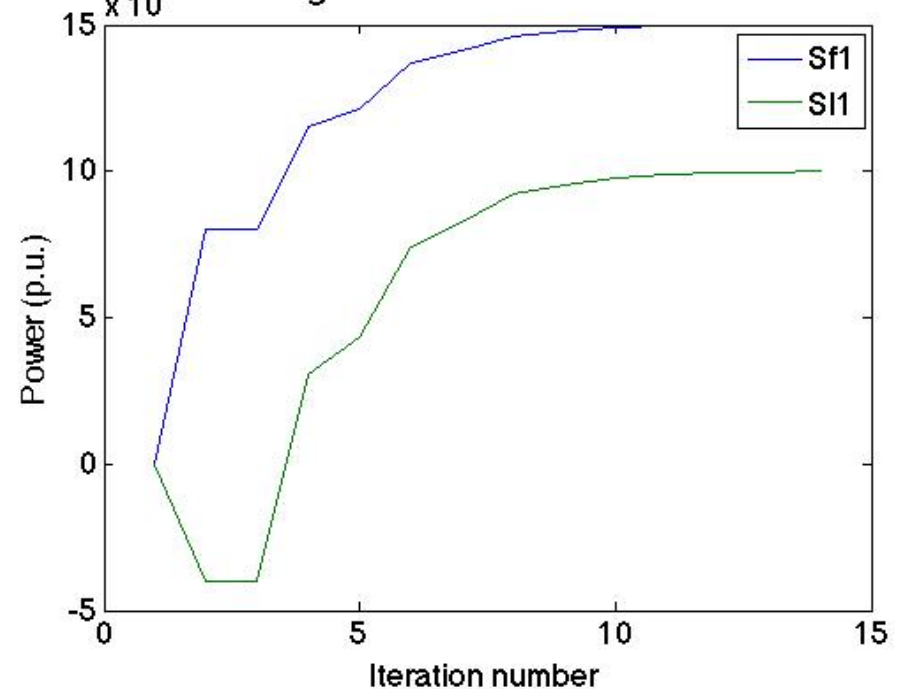


Expected Output

Real{Sf,Sl} per iteration
Real Part of Flows/Losses



Imag{Sf,Sl} per iteration
Imag Part of Flows/Losses



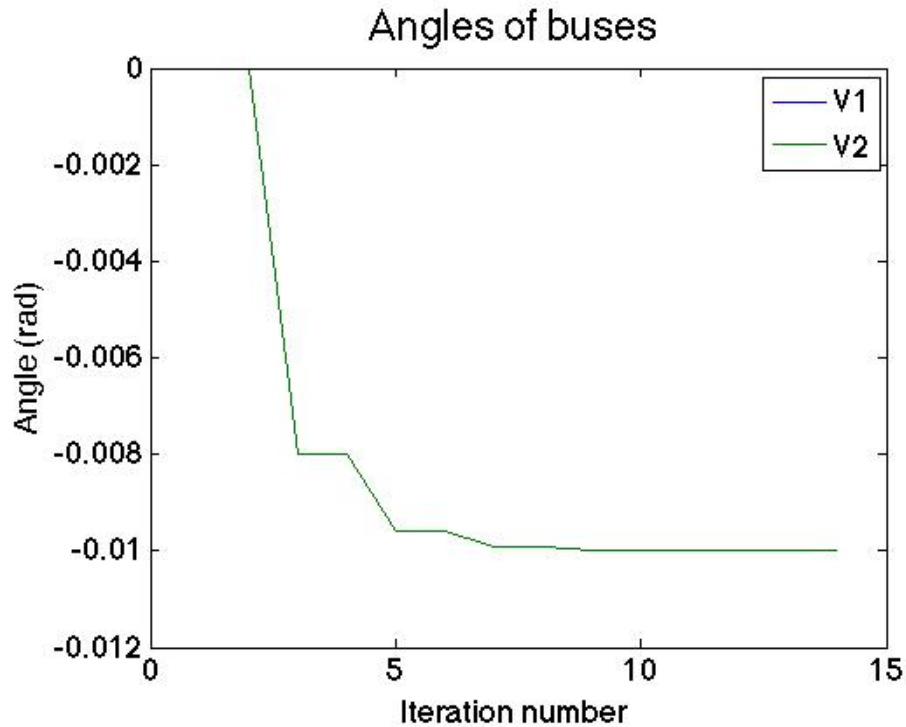
Given:

$$Z = 0.001 + 0.1j$$

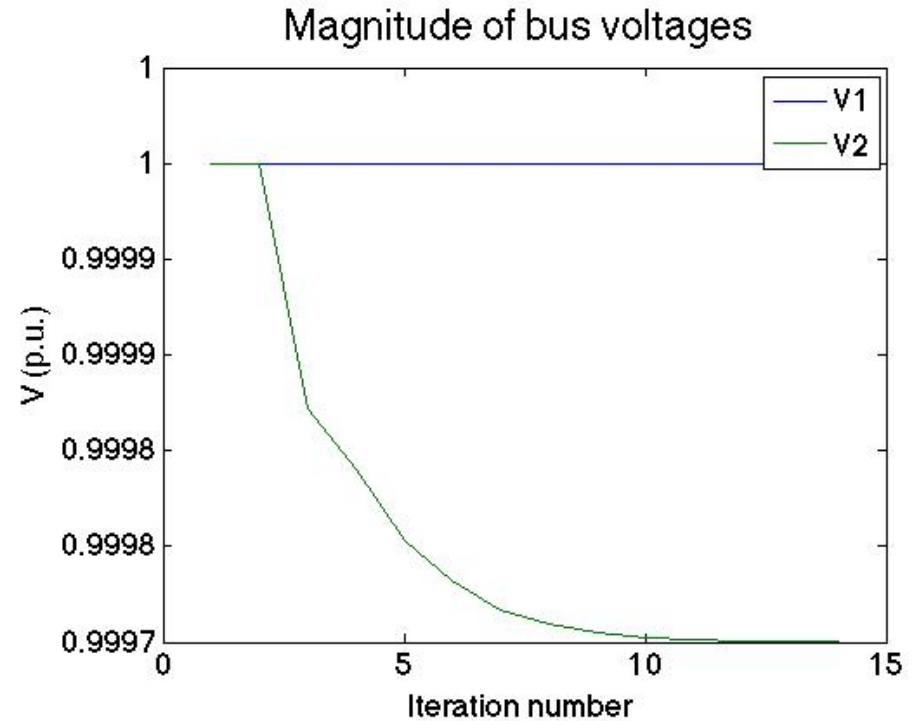
$$\text{Load} = 0.1 + 0.0001j$$

Expected Output of Voltage at Load Bus

angle{V} per iteration

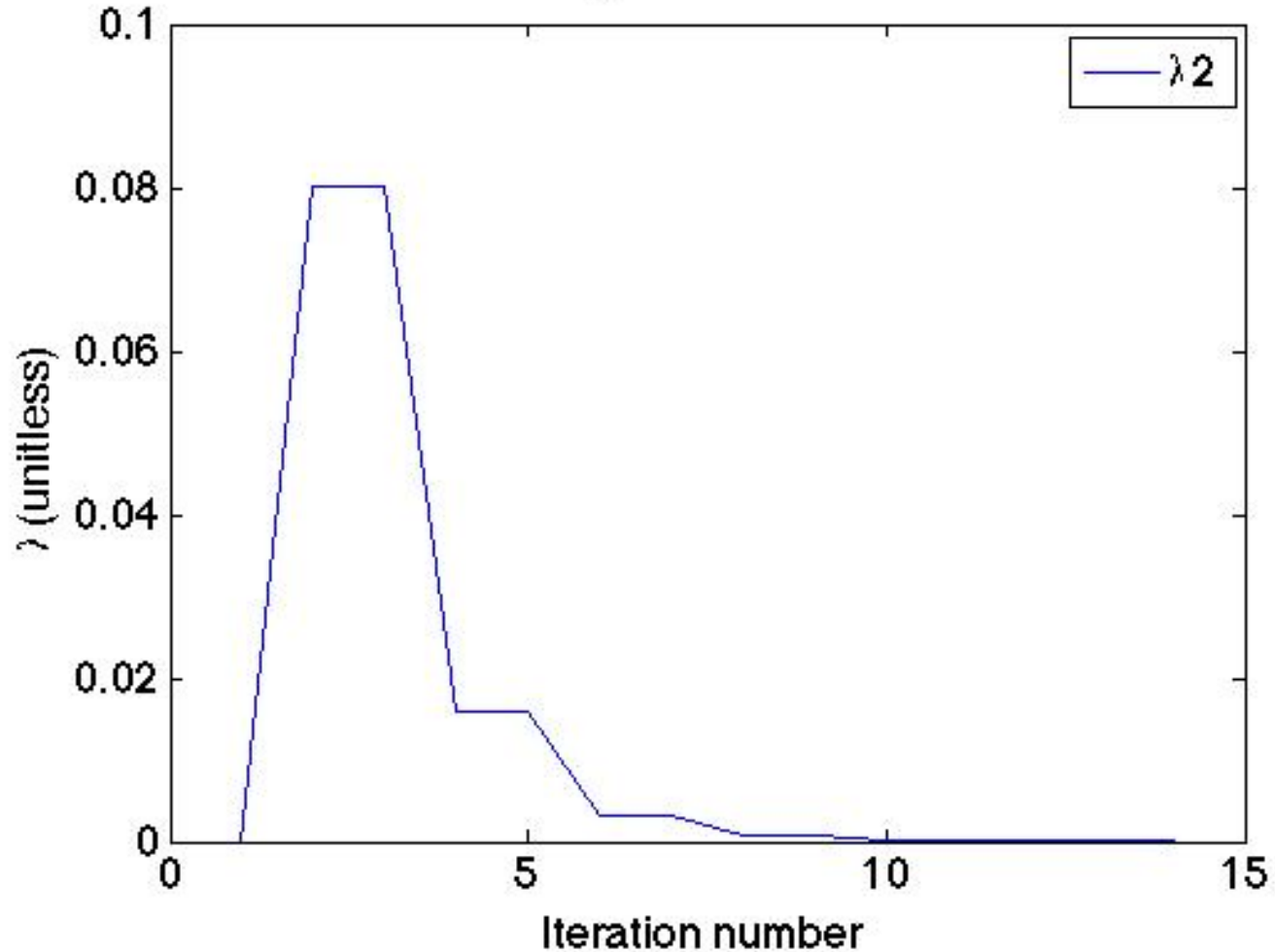


abs{V} per iteration



Expected Output of Lagrange Multiplier at Load Bus

Magnitude of λ



Discussion and Conclusion

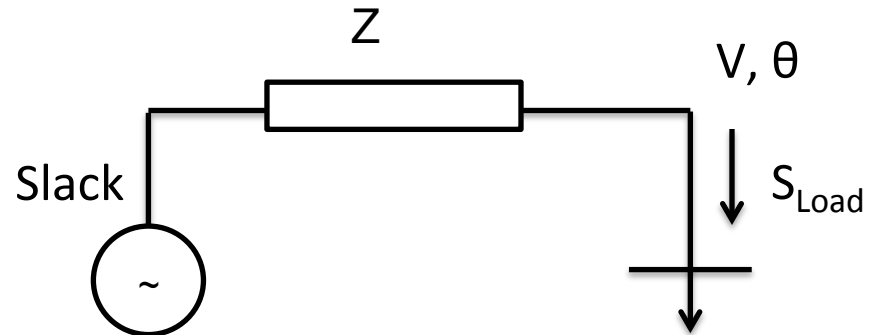
- ❖ **Developed distributed algorithm that runs on lines and buses of an electric power network**
- ❖ **Show that distributed, localized logic can be developed and implemented in the NIST simulations platform**
- ❖ **Show how to conceptualize the algorithm to aid its deployment in the simulations platform**

References

- ¹Hsu, A. and Ilic, M. *Distributed newton method for computing real decoupled power flow in lossy electric energy networks*, North American Power Symposium (NAPS), 2012 , vol., no., pp. 1-7, 9-11 Sept. 2012.
- ²Hsu, A. and Ilic, M. *Toward Distributed Contingency Screening Using Line Flow Calculators and Dynamic Line Rating Units (DLRs)* ,Hawaiian International Conference of System Sciences (HICSS). Maui, Hawaii, January 2012.
- ³Ilic, M. and Hsu, A. *General Method For Distributed Line Flow Computing With Local Communications In Meshed Electric Networks*, Pub. No. US 2013/0024168 A1, January 24, 2013 (status: allowed)
- ⁴Hsu, A., Ilic, M. *Ensuring Feasible Power Delivery Using An Optimization-based Power Flow Model*, Techcon 2013, Austin, Tx. Sept 2013

Infeasible Power Delivery

- ❖ Depending on the line parameters, a voltage solution may or may not exist (voltage instability)
- ❖ It can be solved in closed form for the 2 bus system, but not in multi-bus systems



2 bus system with generator and load

$$\text{real}\{V\} = \frac{1}{2} \pm \frac{1}{2} \sqrt{1 - 4(\text{real}\{Z * S_{Load}\} + \text{imag}\{Z * S_{Load}\}^2)}$$

$$\text{imag}\{V\} = \text{imag}\{Z * S_{Load}\}$$

Equations Slide 1

$$F = S_f - \frac{1}{2} Y^* (V^-) * (2V_{rec} + V^-)$$

$$L = S_l - Y^* (V^-) * (V^-)$$

$$\Delta\lambda = \frac{4}{5} N^{-1} \left(\sum_{neighbors} (dS_f + \frac{1}{2} S_l - dF + \frac{1}{2} L) \right) - b_{inj}$$

where $N = \#$ of connected lines to bus,

$d = -1$ if line orients towards bus, 1 if line orients away

Equations Slide 2

$$\Delta S_f = F + \lambda_{sen} - \lambda_{rec} + \Delta\lambda_{sen} - \Delta\lambda_{rec}$$

$$\Delta S_l = L + \frac{1}{2}(\lambda_{sen} + \lambda_{rec} + \Delta\lambda_{sen} + \Delta\lambda_{rec})$$

$$\Delta V^- = (H_{v2,1} - H_{v2,2}H_{v1,2}^{-1}H_{v1,1})^{-1}(V^- * -H_{v2,2}H_{v1,2}^{-1}V^-)$$

Equations Slide 3

$$H_{v1,1} = 2 \frac{\partial F}{\partial V^-} \frac{\partial F^*}{\partial V^-} + 2 \frac{\partial L}{\partial V^-} \frac{\partial L^*}{\partial V^-}$$

$$H_{v2,1} = \frac{\partial^2 F}{(\partial V^-)^2} F^* + \frac{\partial F^*}{\partial V^-} \left(\frac{\partial F^*}{\partial V^-} \right)^* + \frac{\partial^2 F^*}{(\partial V^-)^2} F + \frac{\partial F}{\partial V^-} \left(\frac{\partial F}{\partial V^-} \right)^*$$

$$+ \frac{\partial^2 L}{(\partial V^-)^2} L^* + \frac{\partial L^*}{\partial V^-} \left(\frac{\partial L^*}{\partial V^-} \right)^* + \frac{\partial^2 L^*}{(\partial V^-)^2} L + \frac{\partial L}{\partial V^-} \left(\frac{\partial L}{\partial V^-} \right)^*$$

$$H_{v1,2} = H_{v2,1}^*$$

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