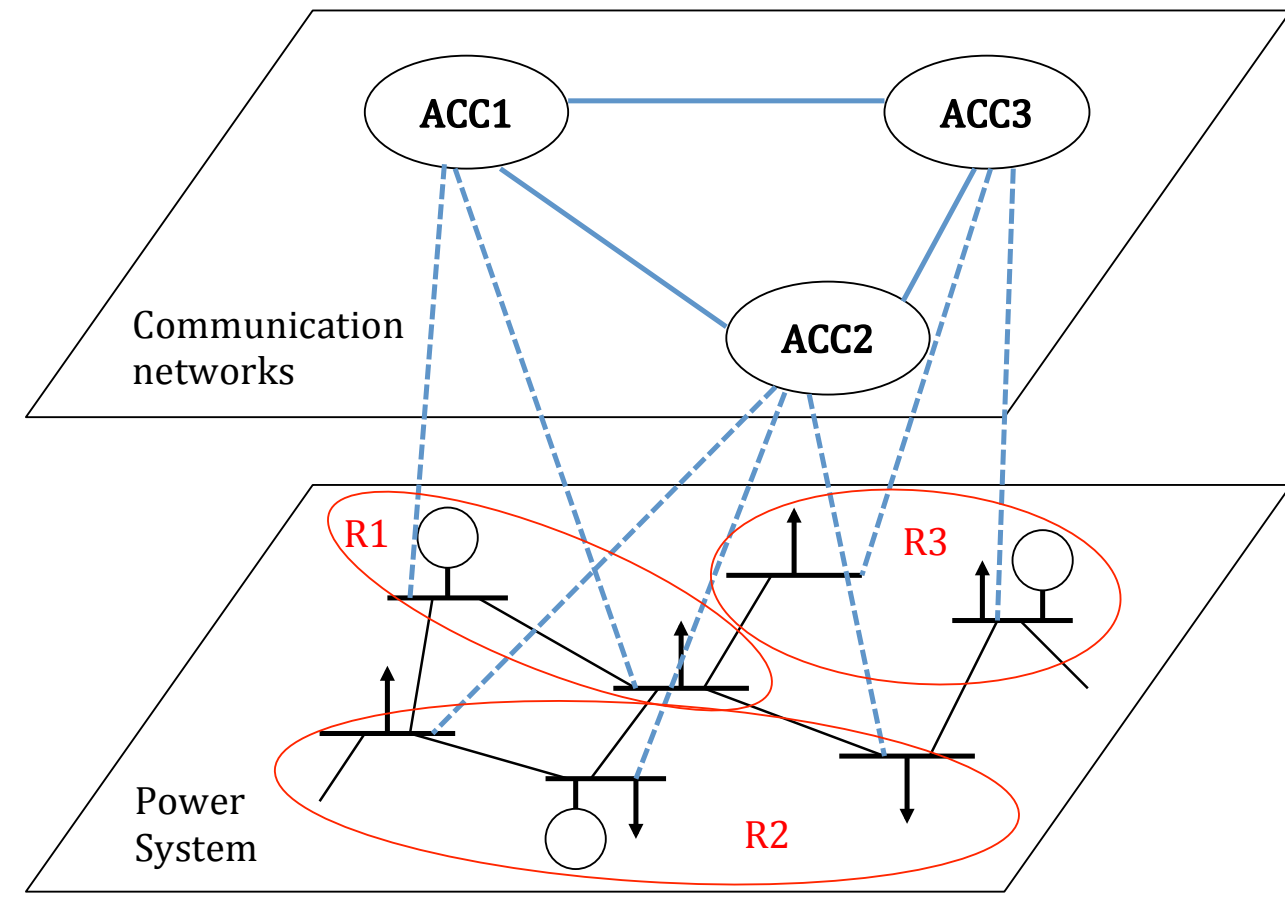


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I. Motivation



❖ Motivation for Distributed Optimization

- Increasing distributed generation and flexible loads
- Increasing scale and complexity of optimization problems

❖ Partitioning in Distributed Optimization

- Unclear impact on distributed optimization
- Indispensable decision for implementation of distributed optimization methods

❖ Our Contributions

- Evaluated how partitioning affects the convergence speed of distributed methods
- Proposed an Intelligent Partitioning method that finds the best partition to speed up distributed optimization

II. Decomposition Method

❖ Optimization Problem

- AC Optimal Power Flow (OPF)

❖ Decomposition Method

- Optimality Condition Decomposition (OCD) ^[1]

$$L = \sum_{a=1}^A [f_a(x_a) + \lambda_a^T c_a(x_1, \dots, x_A) + \gamma_a^T s_a(x_a)]$$

$$H \begin{pmatrix} \Delta \tilde{x}_1 \\ \vdots \\ \Delta \tilde{x}_A \end{pmatrix} = - \begin{pmatrix} \nabla_{\tilde{x}_1} L \\ \vdots \\ \nabla_{\tilde{x}_A} L \end{pmatrix}$$

$$H = \begin{pmatrix} H_{11} & \dots & H_{1A} \\ \vdots & \ddots & \vdots \\ H_{A1} & \dots & H_{AA} \end{pmatrix}$$

III. Intelligent Partitioning

III.A Impact of partitioning on convergence time^[2]

❖ How to evaluate a specific partition of the system?

- Coupling parameter** $c = \rho(I - \bar{H}^{-1}H)$
 - H - Hessian matrix of the Lagrangian function of the partitioned system
 - \bar{H} - Hessian matrix of the ideally decoupled system
 - ρ - Spectral radius

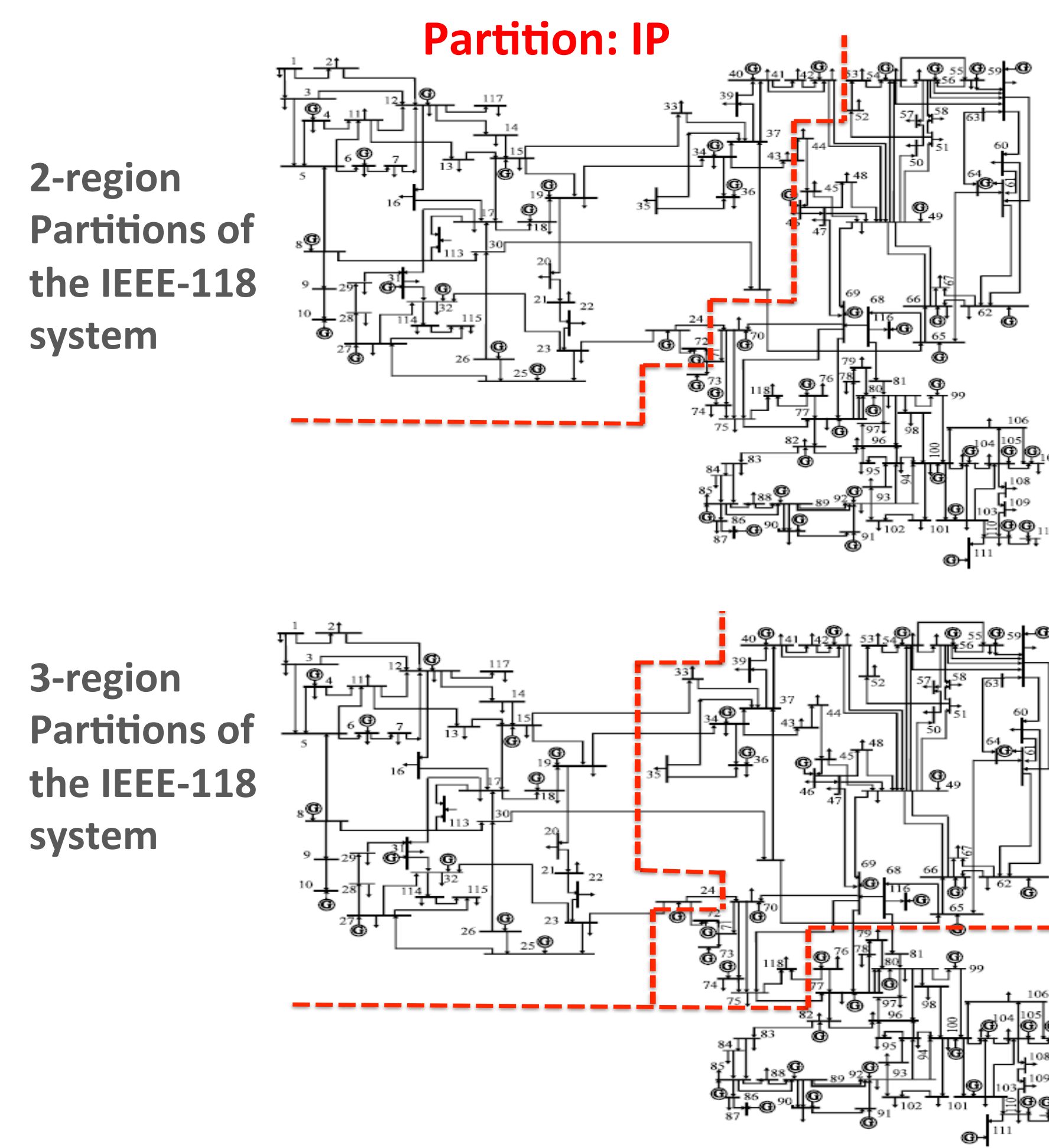
❖ Speed of OCD Using Different Partitions of IEEE-30 System

Partition	Regions	Coupling parameter	Iteration	Time (s)
None	1	N/A	30	0.09
a	2	0.6117	93	0.09
b	2	0.7647	158	0.15
c	3	0.8386	210	0.14
d	3	0.8550	251	0.25
e	4	0.8465	242	0.17
f	4	0.8893	321	0.21

* Convergence time: $t = k \cdot (\max\{t_1, t_2, \dots, t_A\})$

❖ Partitioning greatly affects convergence speed

- Coupling parameter can measure computational coupling between partitioned areas
- The smaller the c , the faster the convergence
- H is closer to block diagonal $\rightarrow c$ is smaller



III.B An intelligent partitioning method

Group the strongly computationally coupled buses!

❖ Affinity between buses

- The entry H_{ij} in H_{sys} is non-zero \rightarrow Variables with indices i and j are computationally coupled
- More than two variables associated with any two buses i and j

$$A_{i,j} = \sum_{m \in \Omega_i} \sum_{n \in \Omega_j} |H_{m,n}|$$

❖ Implementation

• Step 1 Initialization

- Derive the Hessian matrix of the Lagrangian function of the unpartitioned power system at optimality

• Step 2 Calculation of the affinity matrix

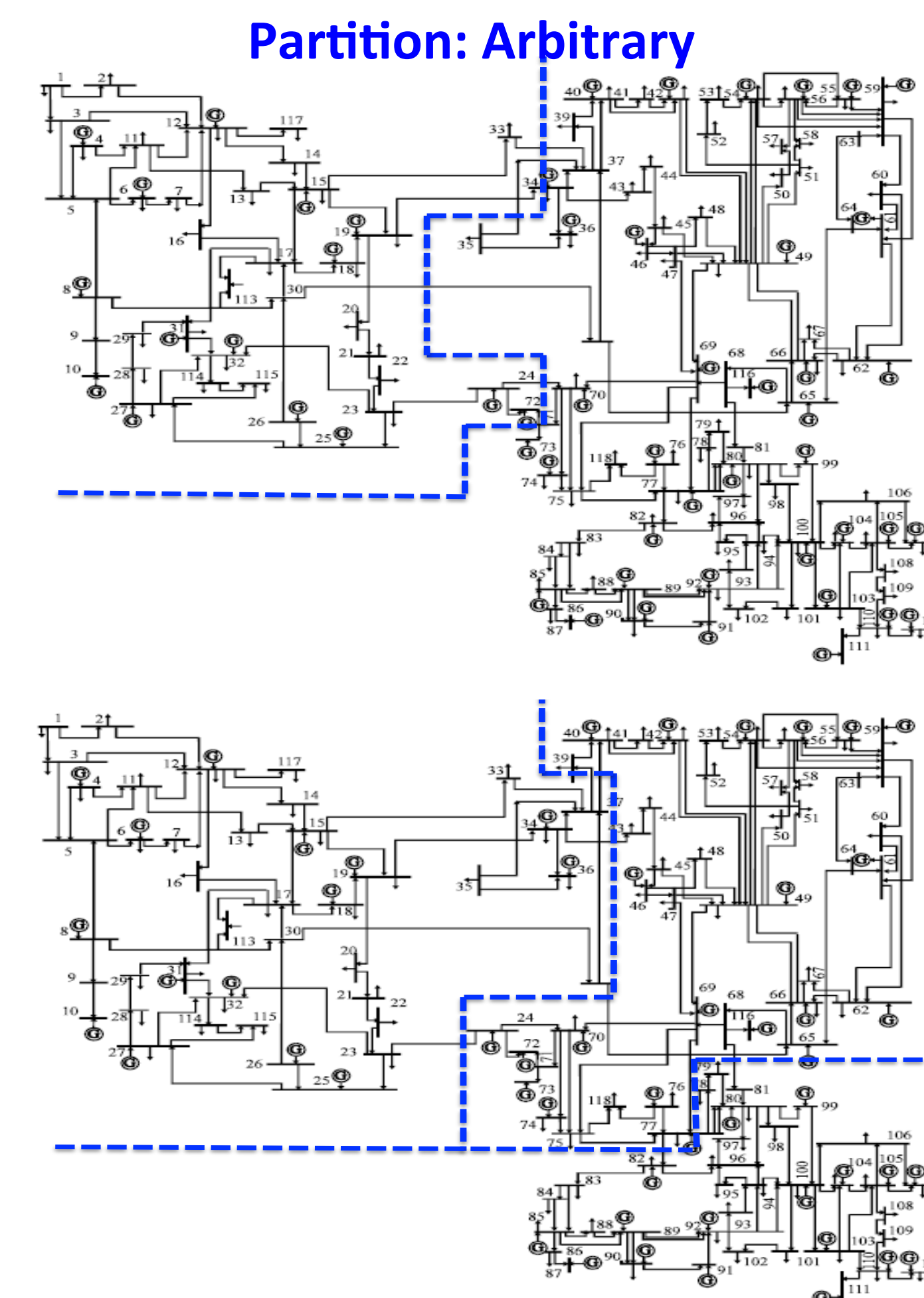
• Step 3 Clustering

- Cluster the buses into subregions using spectral clustering ^[2] based on the affinity matrix

- More than one possible solutions

• Step 4 Selection

- Compute the coupling parameter of all partitions
- Select the partition with minimum c



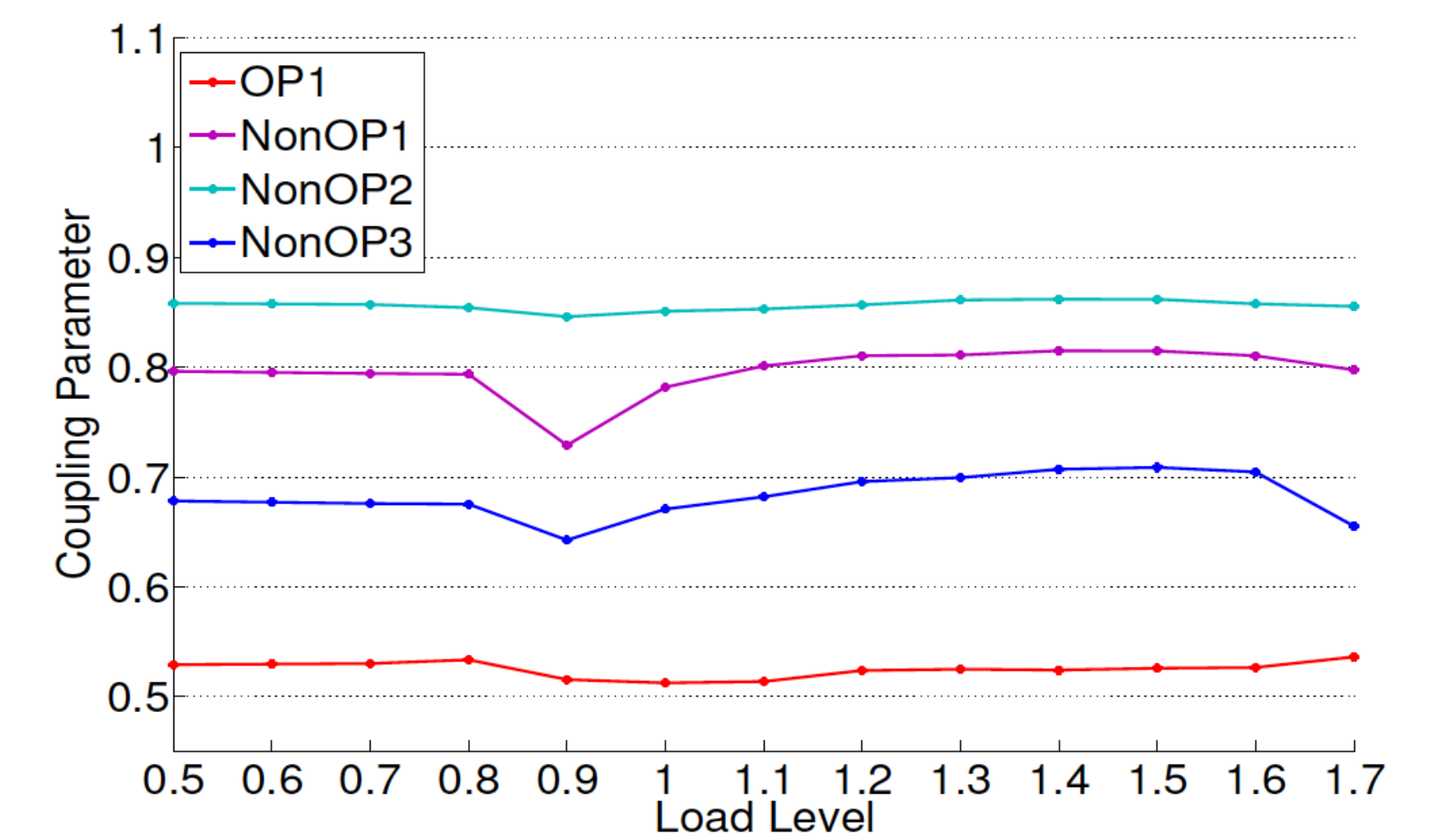
IV. Simulation Results

❖ Convergence Speed-up Using Different Partitions of IEEE-118 System

#	Partition: IP				Partition: Arbitrary			
	c	k	$t(s)$	Speed-up	c	k	$t(s)$	Speed-up
2	0.51	105	3.4	11%	0.72	197	8.9	-134%
3	0.79	225	2.3	39%	0.91	454	4.3	-13%
4	0.79	246	1.4	63%	0.89	378	3.0	21%
5	0.82	250	1.3	66%	0.87	330	2.1	45%

- Centralized Approach: Iterations $k=33$, Convergence Time $t=3.8s$

❖ Robustness of the Best Partition to Operating Points



V. Conclusions

❖ Conclusions

- Partitioning significantly affect the convergence speed of the decomposition method
- Convergence is considerably sped-up using the partition computed by the proposed method

❖ Future Works

- Evaluate the impact of partitioning on other performances of distributed methods such as information exchange
- Generalize the Intelligent Partitioning method for other decompositions methods

References

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