



On The Challenges Related To Using Thermostatically Controlled Loads For Demand Response

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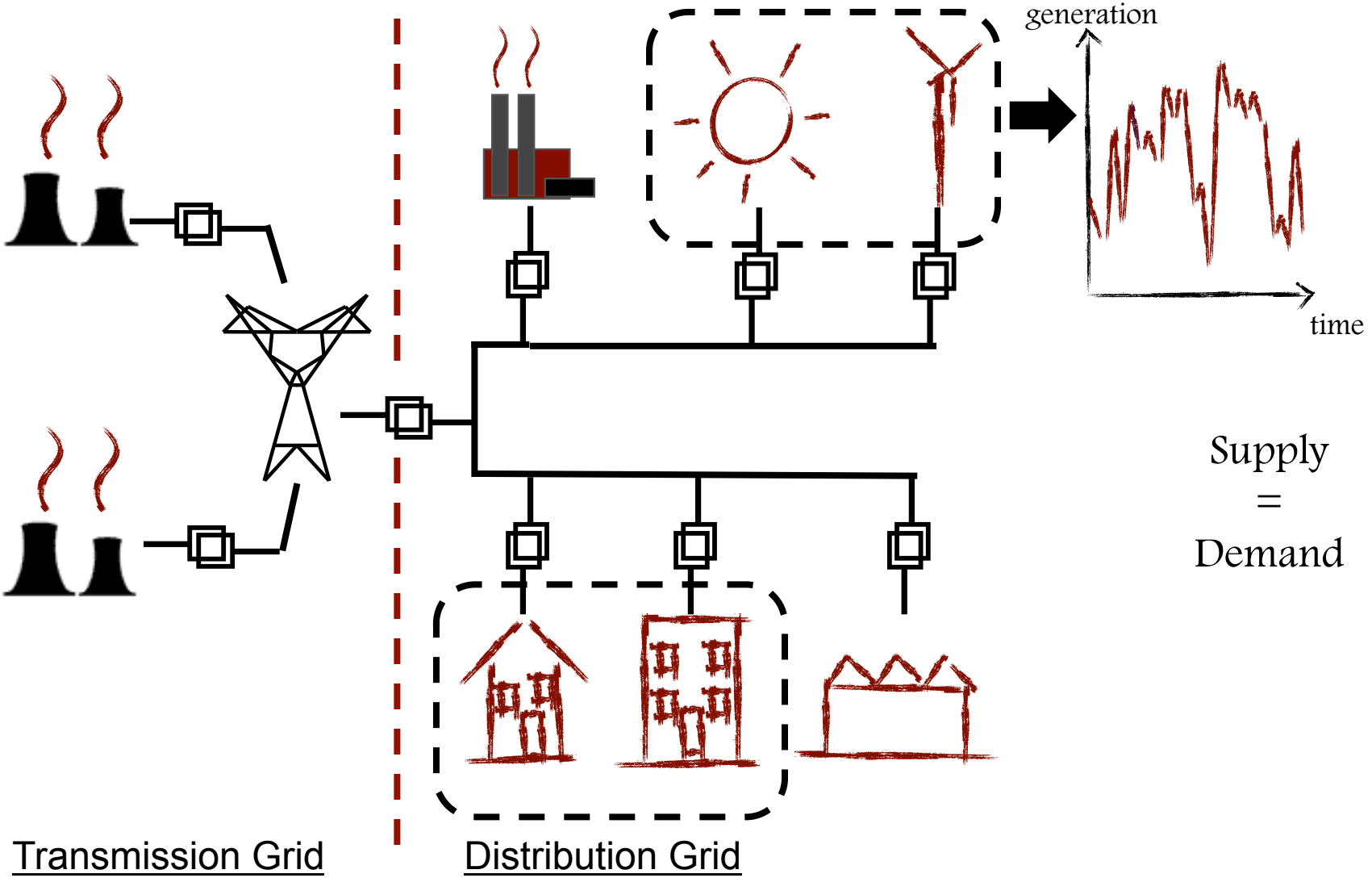
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Civil & Environmental
ENGINEERING
Carnegie Mellon

Collaborators

- Emre Can Kara (CEE, student)
- Bruce Krogh (ECE)
- Zico Kolter (CS)
- Soumya Kar (ECE)
- Gabriela Hug (ECE)

Renewable Energy



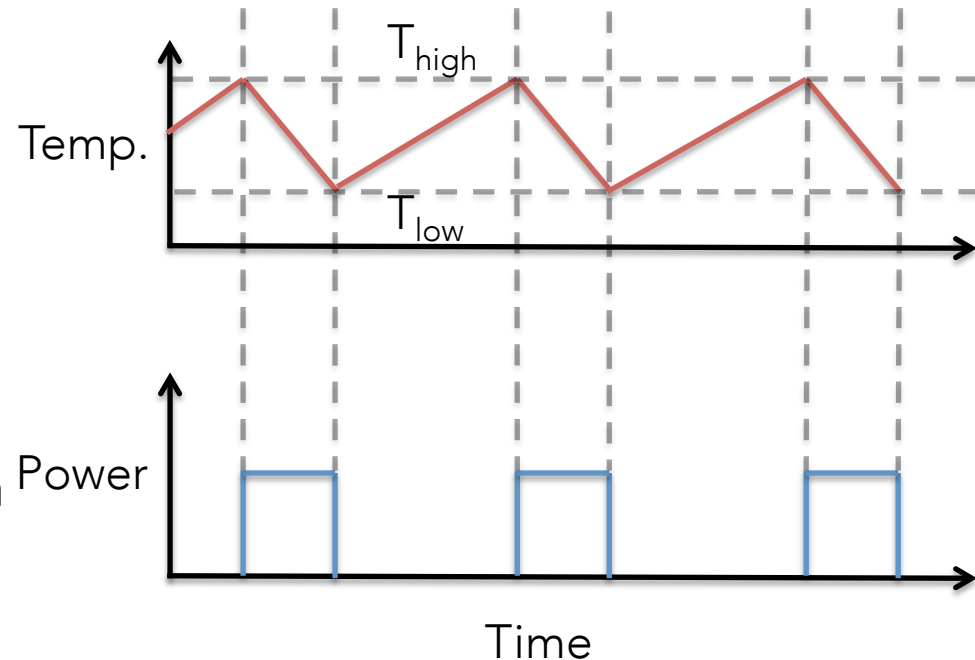
Flexibility and Reliability: Additional Sources

- Demand response systems
 - Price responsive demand
 - Variation in price to encourage customers to reduce/shift consumption
- Load management and control
 - Loads are automated and controlled directly based on a control signal
 - Tighter control bounds
 - Faster response time
 - provide fast-timescale (seconds to minutes) services

Thermostatically Controlled Loads (TCLs)

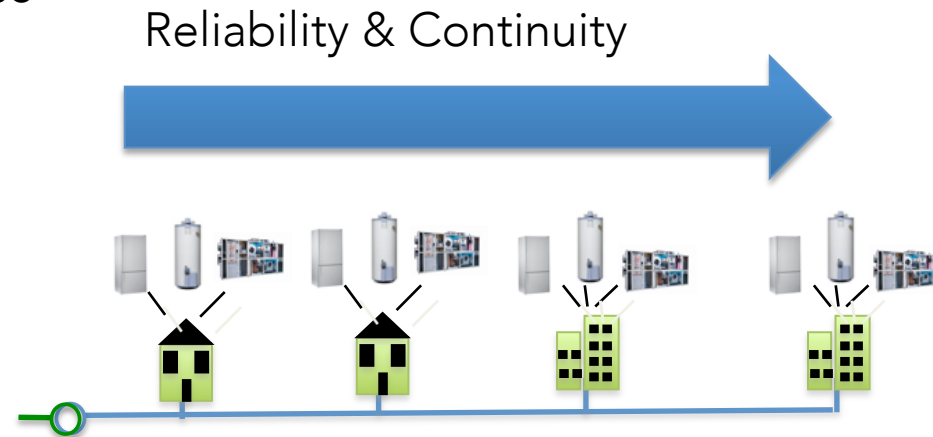
- More than 40% of the electricity consumed in buildings
- Availability in households
- 24/7 available for signals
- Disrupted without any effect on end-user's comfort

Refrigeration example:



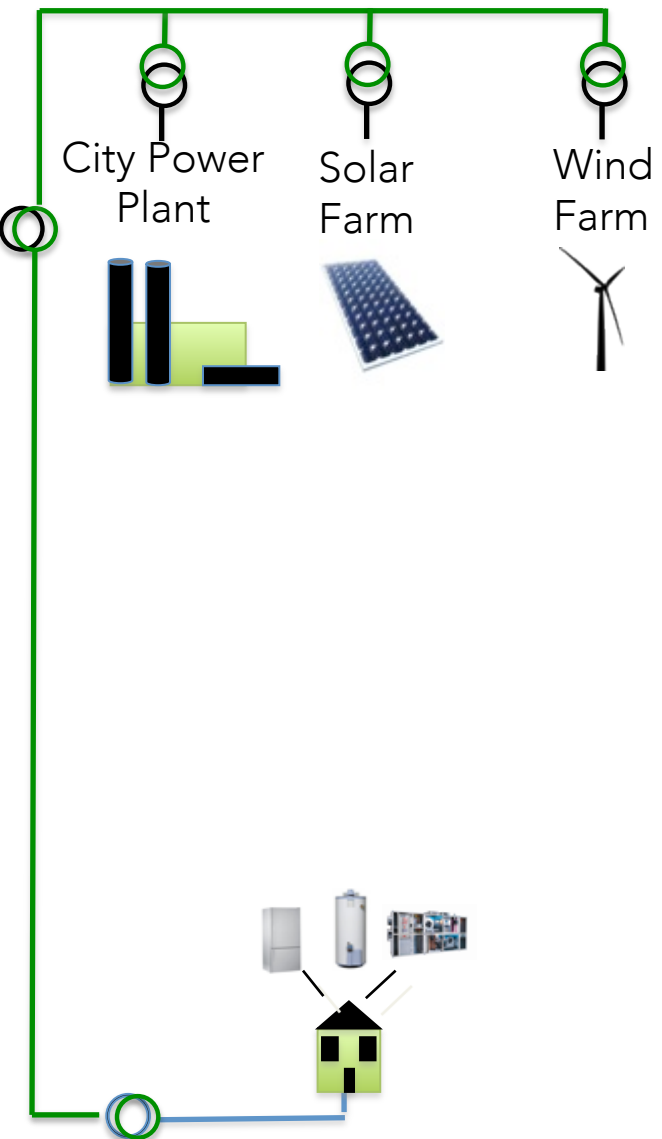
Load Aggregation Benefits

- An aggregation of smaller loads provide **more reliable curtailment** than the response of a single or multiple large loads with an equivalent capacity. (Eto et al. 2012)
- Aggregations of small load resources provide **continuous control** with simpler control actuation. (Callaway et al. 2011)
- Individual monitoring systems for small loads are expected to **be less costly** than large load programs.



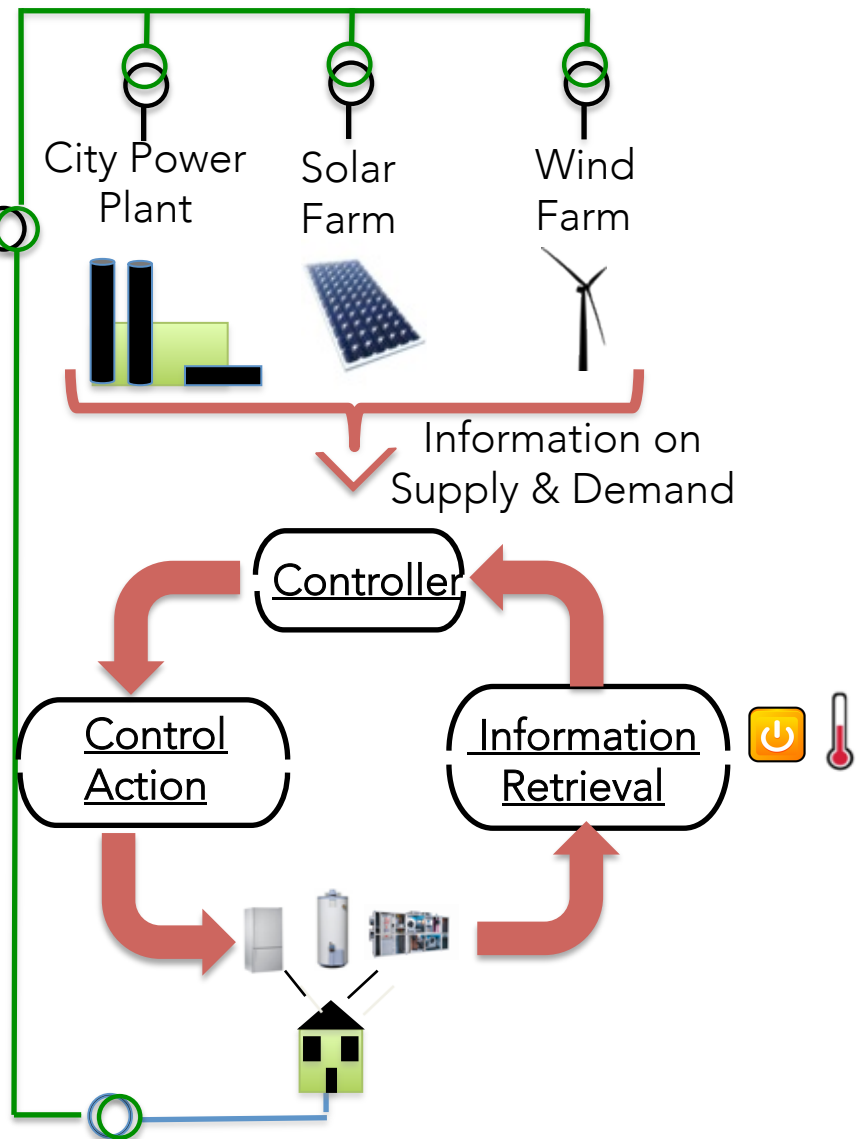
Existing Work

Centralized Control

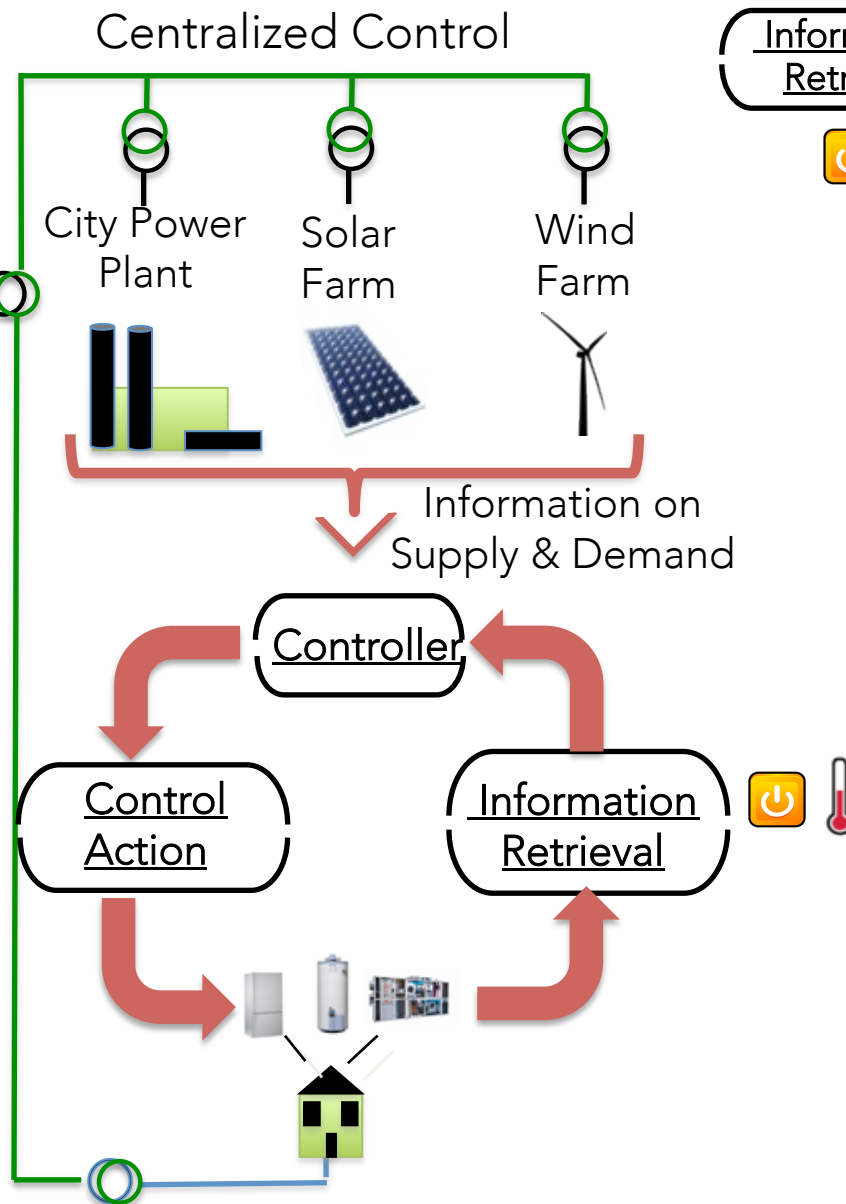


Existing Work

Centralized Control







Existing Work



Information Retrieval

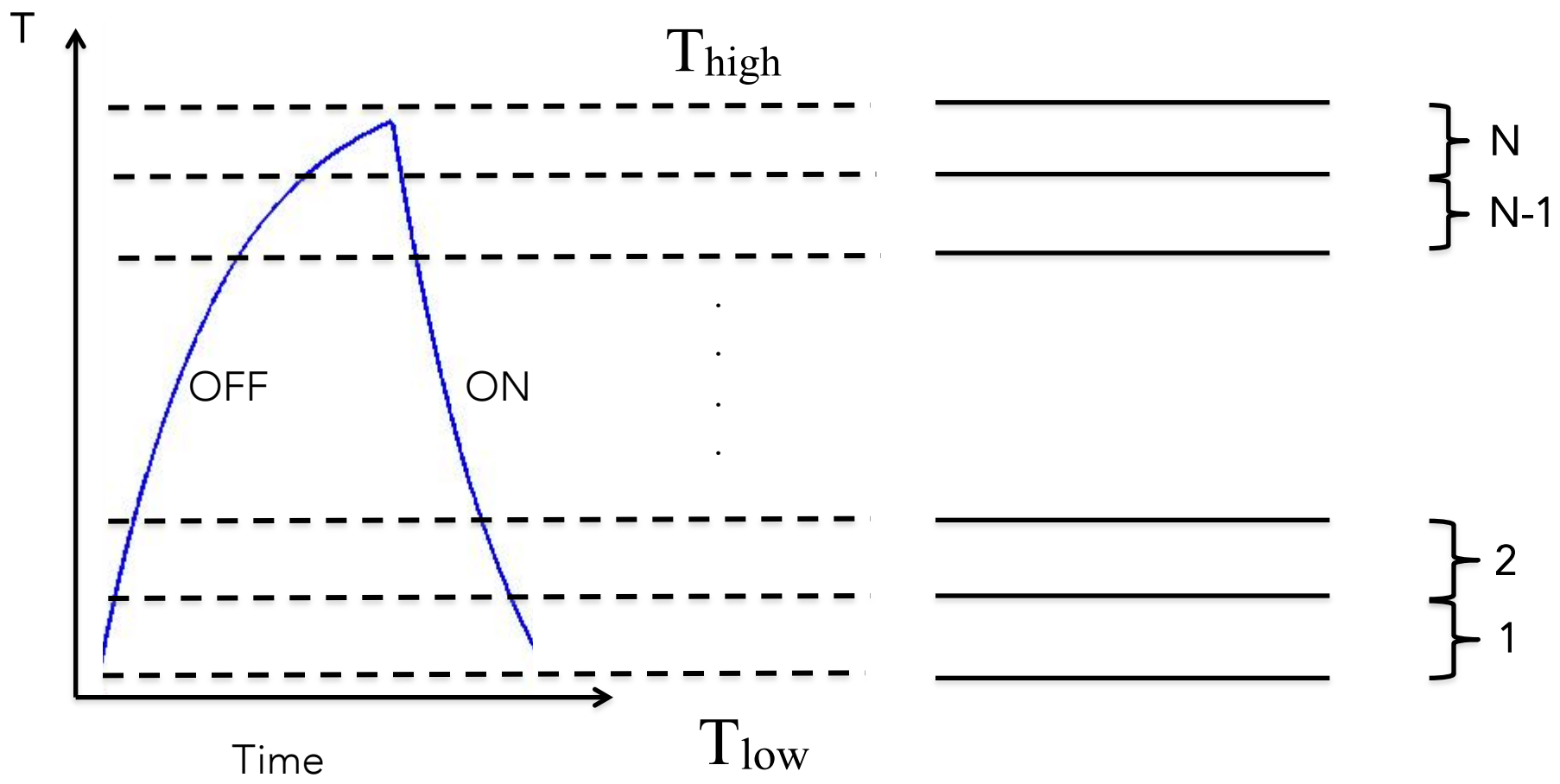


- Real-time state information  from appliances. (Koch et al. 2011; Kara et al. 2012) 
- Kalman filter and Extended Kalman filter for estimation. (Mathieu et al. 2012)

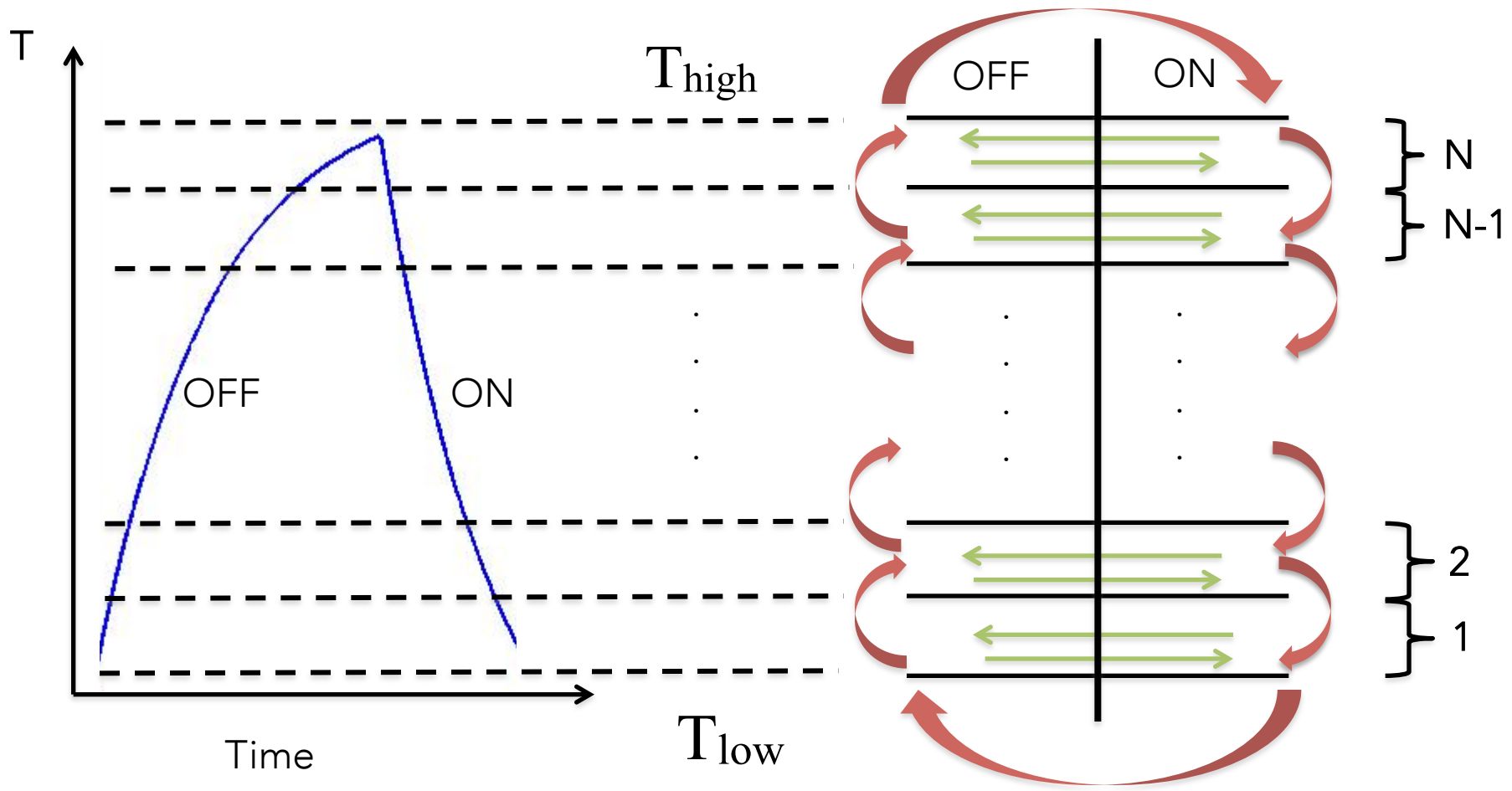
Aggregate Power  State Information 

CHALLENGE #1: STATE ESTIMATION

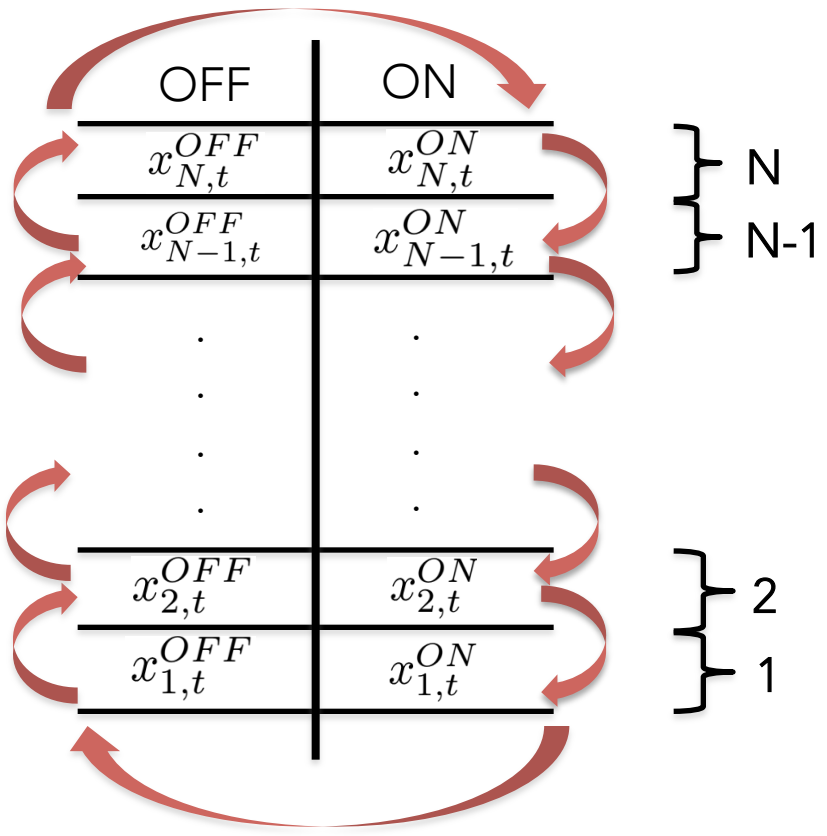
Population Model



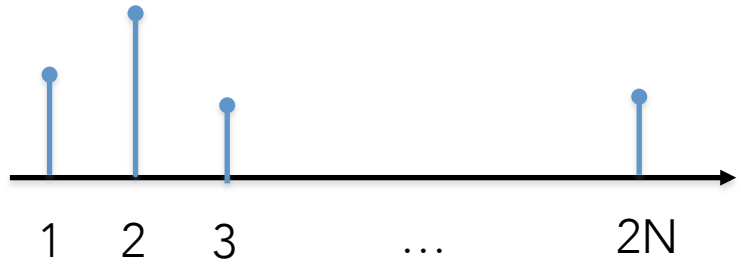
Population Model



Population Model



- State Vector: Probability of being in a bin



$$X_t = [x_{1,t}^{ON}, \dots, x_{N,t}^{ON}, x_{1,t}^{OFF}, \dots, x_{N,t}^{OFF}]$$

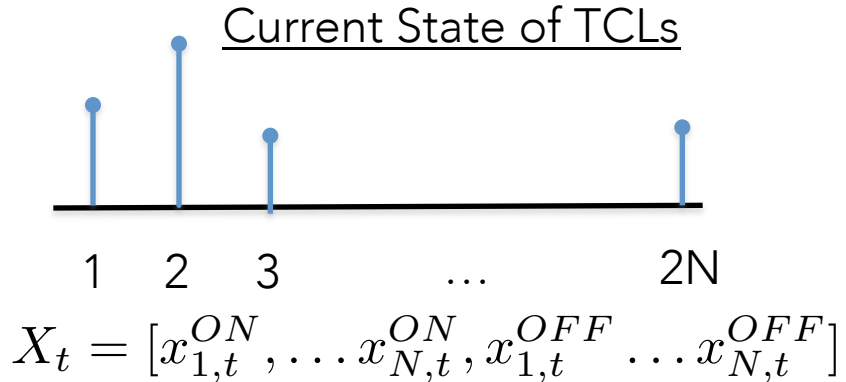
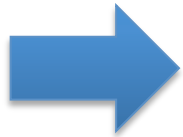
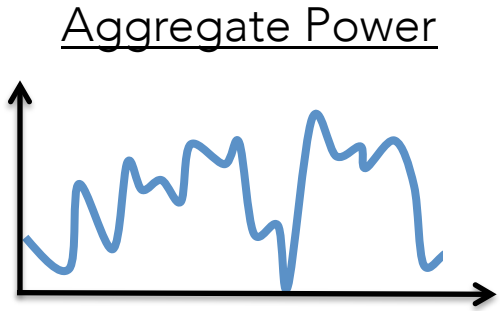
- Control Action: Switching Probabilities

$$d_{k,t}^0 = \mathbf{P}\{S_{t+1} = ON | S_t = OFF, I_t = k, controller\}$$

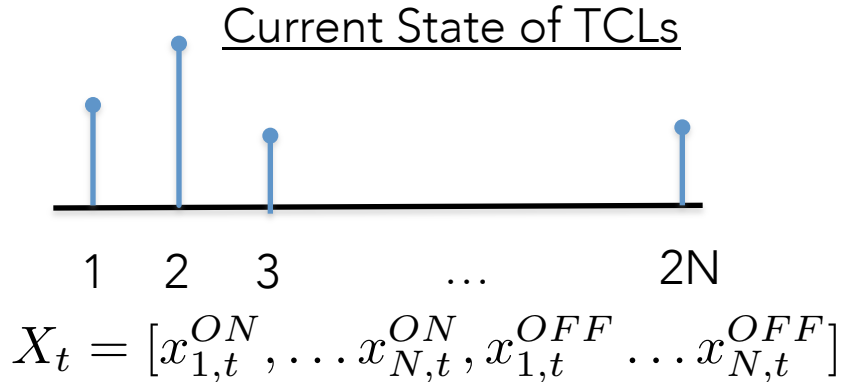
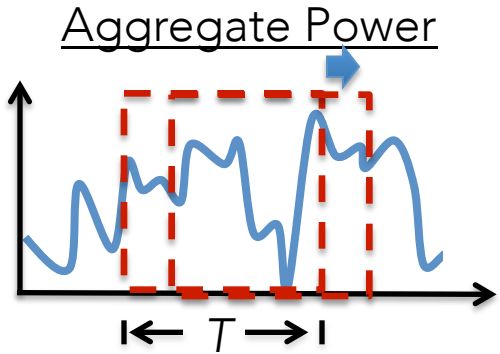
$$d_{k,t}^1 = \mathbf{P}\{S_{t+1} = OFF | S_t = ON, I_t = k, controller\}$$

$$D_t = [d_{1,t}^\xi, \dots, d_{N,t}^\xi]$$

State Estimation



State Estimation



- Using system dynamics based on Kara et al. 2012

$$X_{t+1} = \mathfrak{T}(D_t, X_t)$$

- Assume C exists such that:

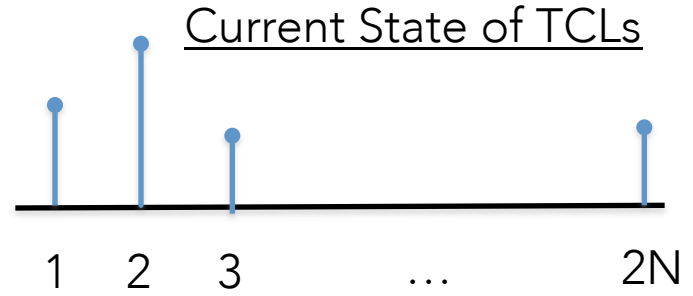
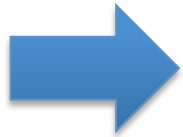
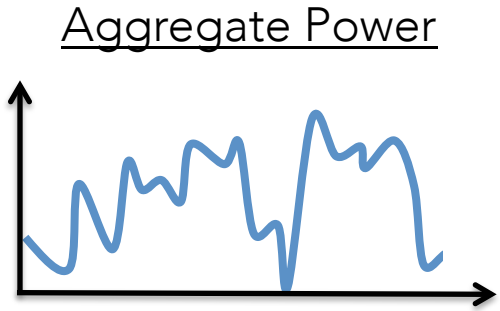
$$Y_t = CX_t.$$

$$\text{minimize}_{\hat{X}_j} \sum_{j=t-T+1}^t (Y_j - \hat{Y}_j)^2$$

subject to

$$\left. \begin{aligned} \hat{X}_j &= \mathfrak{T}(\hat{X}_{j-1}, D_{j-1}) \\ \hat{x}_{j,i}^{ON} &\geq 0 \\ \hat{x}_{j,i}^{OFF} &\geq 0 \\ \hat{X}_j \vec{1} &= 1 \end{aligned} \right\} \begin{aligned} j &\in [t-T+1, t], \\ i &\in [1, N] \end{aligned}$$

State Estimation



$$X_t = [x_{1,t}^{ON}, \dots, x_{N,t}^{ON}, x_{1,t}^{OFF}, \dots, x_{N,t}^{OFF}]$$

- Using system dynamics based on Kara et al. 2012

$$X_{t+1} = \mathfrak{T}(D_t, X_t)$$

- Assume C exists such that:

$$Y_t = CX_t$$

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- Using a liner model based on Callaway et al. 2012

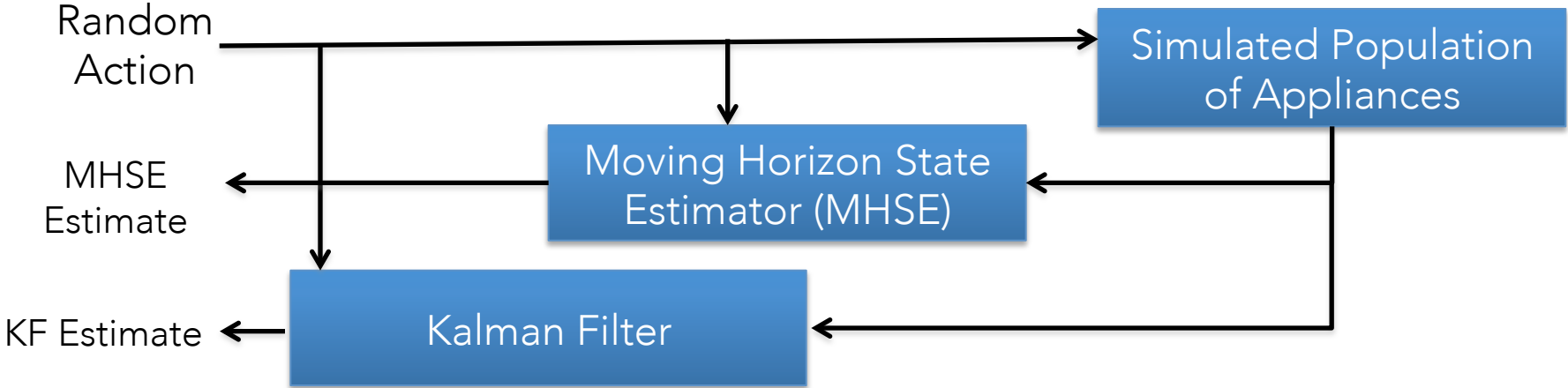
$$X_{t+1} = A_{lin}X_t + Bu_t + B_\omega\omega_t$$

$$Y_t = CX_t + v_t$$

- With perfect measurement noise and the process noise given as follows:

$$p(\omega_t) \sim N(0, Q)$$

Case Studies



Case Study I: Understand the effect of changing the time horizon T on estimation performance for MHSE

Case Specific Input	Distribution	Values
Time Horizon, T	Constant	10, 20, 30, 40, 50, 60 minutes

Case Study II: Compare the performances of the Kalman Filter and the MHSE under different switching conditions.

Case Specific Input	Distribution	Values
Time Horizon, T	Constant	40 minutes
Forcing Parameter, f	Constant	12.5, 25, 50, 75, 100%

Case Studies (Cont'd)

- Simulated 500 TCLs with varying thermal characteristics and white noise on the individual appliance temperature dynamics.

Simulation Input	Distribution	Values
Capacitance	Uniform	[8-12 kWh/°C]
Resistance	Uniform	[1.5-2.5 °C/kW]
Rated Power	Uniform	[10-18 kW]
Temperature Set-point	Constant	20°C
Temperature Deadband Width	Constant	0.5°C
Ambient Temperature	Constant	32°C
Temperature Dynamics Noise	Normal	N(0,0.01)
Simulation Time Step	Constant	1 minutes
Total Estimation Duration	Constant	10 hours

- Estimator specific characteristics:

Kalman Filter	Distribution	Values
Process Noise	Normal	N(0,Q)
Measurement Noise	Constant	0

Case Studies (Cont'd)

- To quantify the information lost when \hat{X}_t is used to represent X_t :

$$D_{KL}(X_t || \hat{X}_t) = \sum_i^{2N} \ln \left(\frac{x_{i,t}}{\hat{x}_{i,t}} \right) x_{i,t}$$

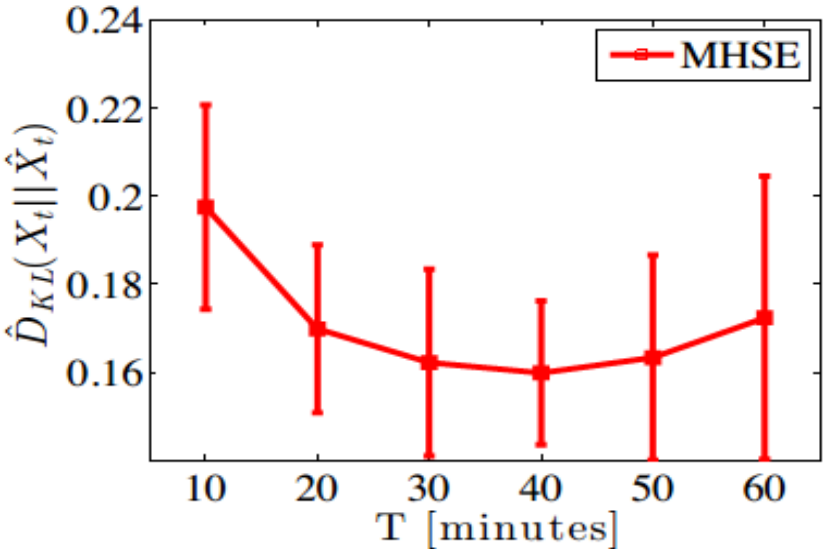
- Mean Kullback-Liebler (KL) divergence during the estimation period for each

run.

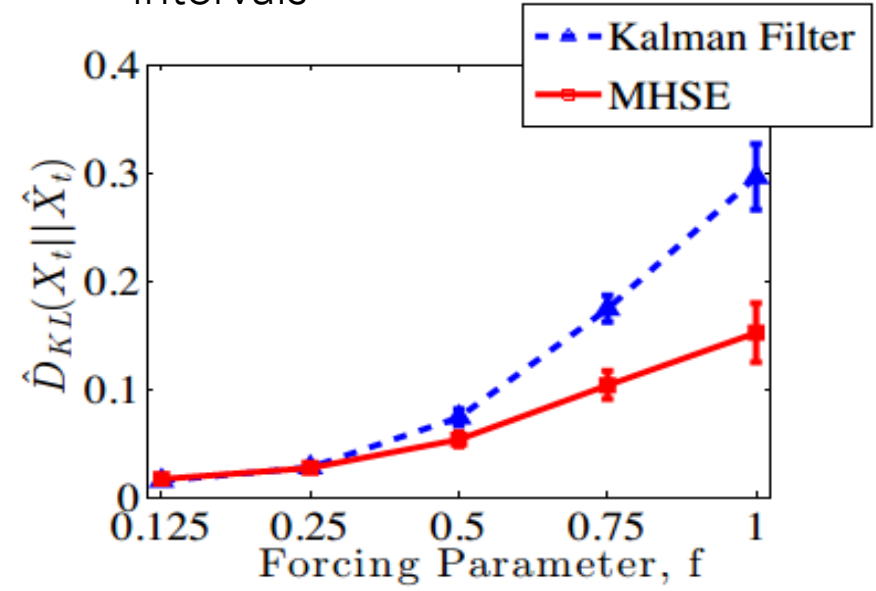
$$\hat{D}_{KL}(X_t || \hat{X}_t) = \frac{\sum_{t=0}^{T_{tot}} D_{KL}(X_t || \hat{X}_t)}{T_{tot}}$$

Results

- Case study I: 10 simulations per estimation horizon
- Showing 95% confidence intervals



- Case study II: 10 simulations per forcing parameter, f
- Showing 95% confidence intervals



CHALLENGE #2: DEVIATIONS FROM LINEAR ASSUMPTIONS

Back to the assumptions

- Simulated 500 TCLs with varying thermal characteristics and white noise on the individual appliance temperature dynamics.

Simulation Input	Distribution	Values
Capacitance	Uniform	[8-12 kWh/°C]
Resistance	Uniform	[1.5-2.5 °C/kW]
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- Estimator specific characteristics:

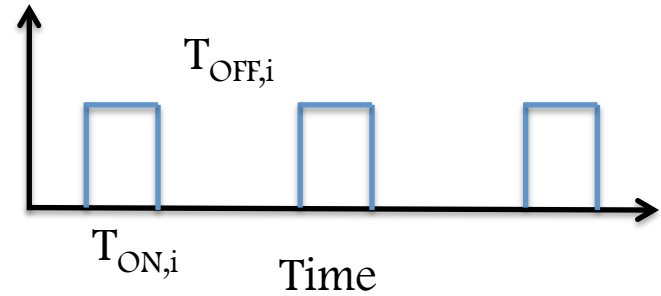
Kalman Filter	Distribution	Values
Process Noise	Normal	N(0,Q)
Measurement Noise	Constant	0



Power consumption data collected over 200 refrigerators.



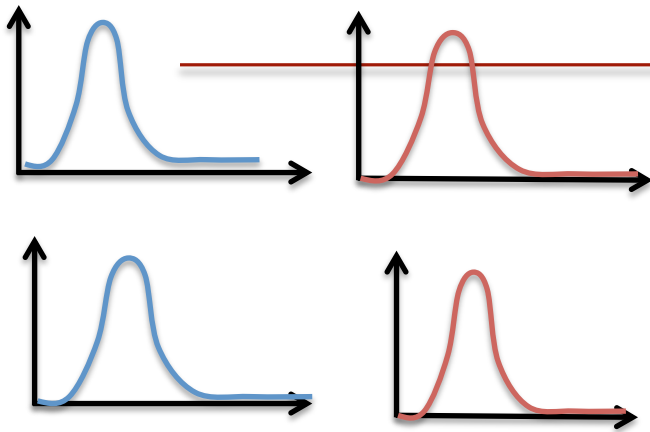
Power



Fit Weibull distributions and obtain parameters



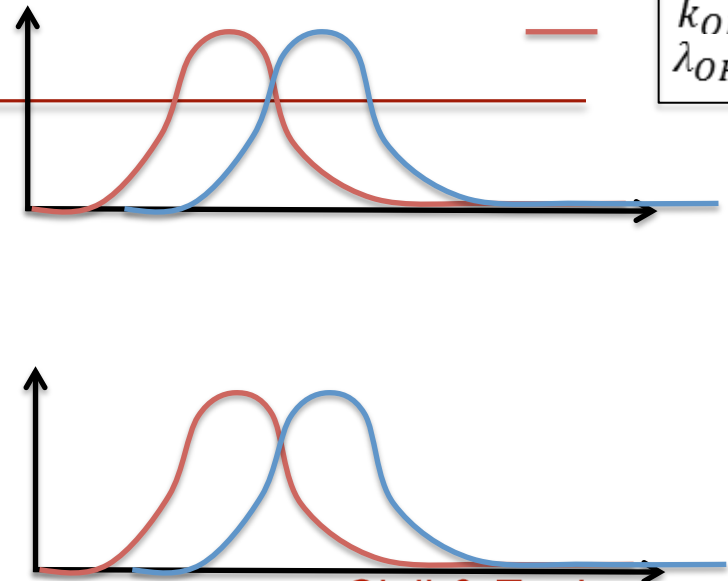
Estimate hyper parameters of k_{ON} , λ_{ON} , k_{OFF} , λ_{OFF}



$i=1$

\vdots

$i=N$



Parameter	Distribution	Range
Thermal Resistance, R_i (°C/kW)	Uniform	80-100
Thermal Capacitance, C_i (kWh/°C)	Uniform	0.4-0.8
Rated Power, $P_{\text{rated},i}$ (kW)	Uniform	0.2-1.0
Ambient Temperature, $\Theta_{i,a}$ (°C)	Constant	20
Thermostatic dead-band, δ_i (°C)	Uniform	1-2
Temperature set point, $\Theta_{i,\text{set}}$ (°C)	Uniform	1.7-3.3

$$\hat{c}_{v,R} = S_R / \bar{R} \quad \hat{c}_{v,C} = S_C / \bar{C}$$

Population	\bar{R} (°C/kW)	\bar{C} (kWh/°C)	S_R (°C/kW)	S_C (kWh/°C)	$\hat{c}_{v,R}$	$\hat{c}_{v,C}$
P1	419.41	0.07	9205.7	0.07	21	1
P2	90.00	0.60	175.76	0.12	0.06	0.19

References

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Acknowledgments

PIA



The End

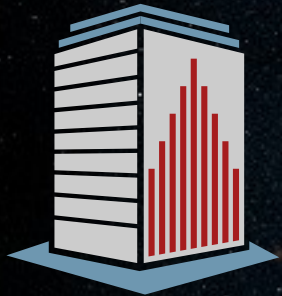
QUESTIONS?



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